

## Midwest Dynamics and Group Actions

Indiana U. /U. of Chicago/U. of Illinois at Chicago/Northwestern U. /U. of Michigan

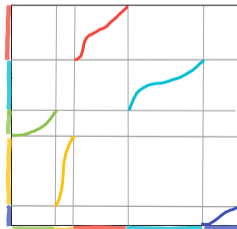
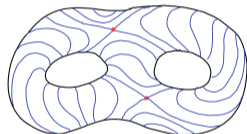
7 June, 2021

# Rigidity of foliations on surfaces and renormalization

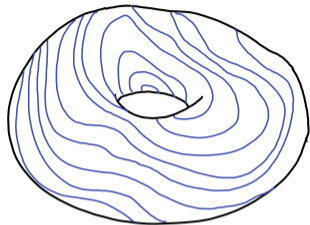
Corinna Ulcigrai

University of Zürich

(joint work with [Selim Ghazouani](#))

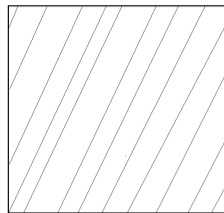
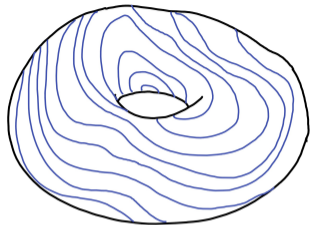


## Rigidity of foliations in genus one.



- ▶  $\mathcal{F}$  orientable smooth foliation of compact  $S$  with  $g = 1$ .
- ▶  $\mathcal{F}$  minimal

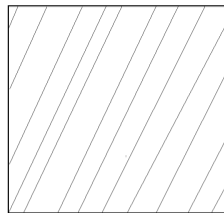
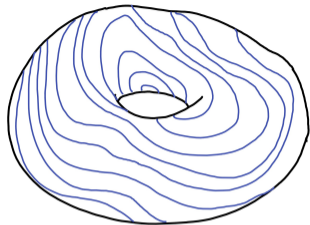
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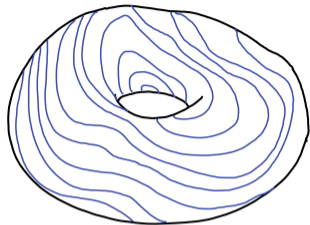
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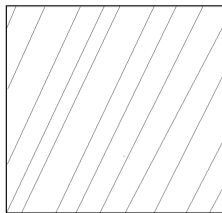
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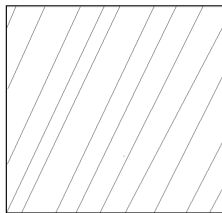
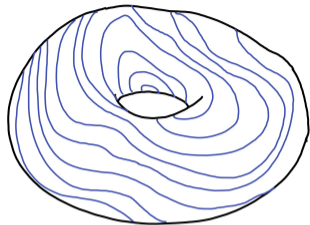


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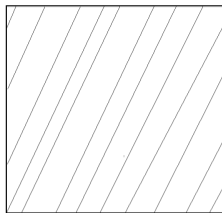
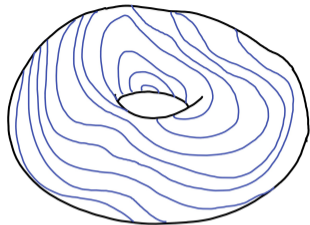
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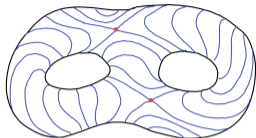
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  - ▶ For a full measure set of rotation numbers (i.e. for a.e.  $\alpha$ ) foliations in  $g = 1$  are geometrically rigid [follows from M. Herman global theorem on circle diffeos.]
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## Rigidity of foliations in genus two.



- ▶  $\mathcal{F}$  orientable smooth foliation of compact  $S$  with  $g = 2$  with only Morse type saddles;

[Morse type (simple) saddles:  
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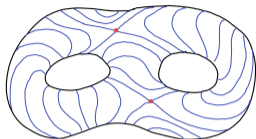
Theorem (Ghazouani-U', 2021)

*Under a full measure arithmetic condition, if  $\mathcal{F}$  is topologically conjugate to  $\mathcal{F}_0$ , then it is differentiably conjugate to it, i.e.  $\mathcal{F}$  is geometrically rigid.*

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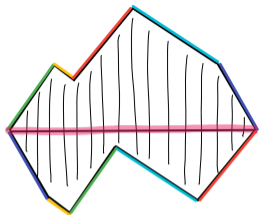
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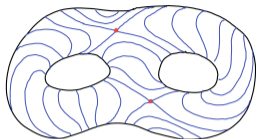
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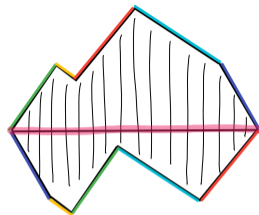
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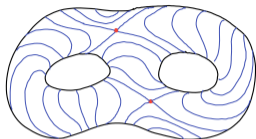
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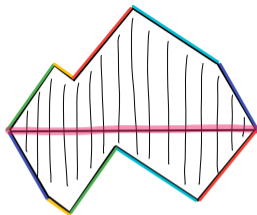
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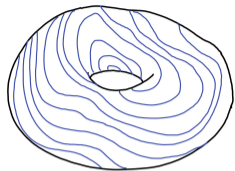
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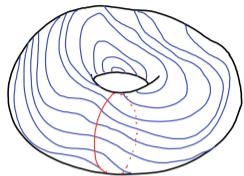
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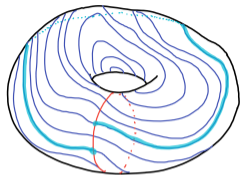
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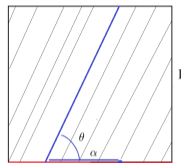
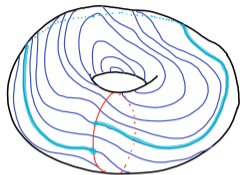
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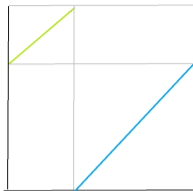
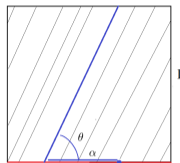
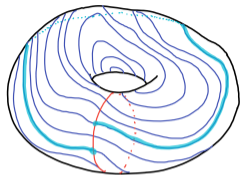
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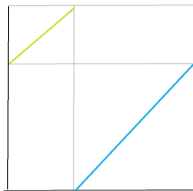
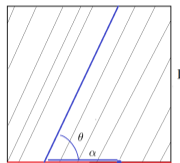
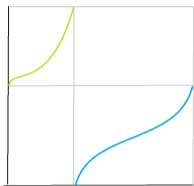
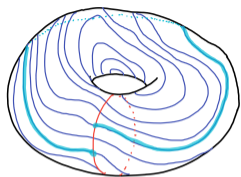


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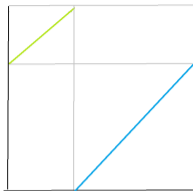
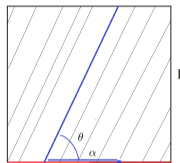
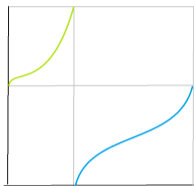
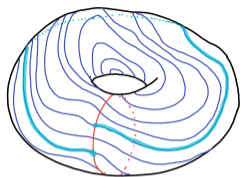
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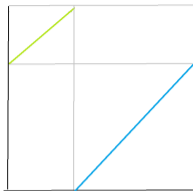
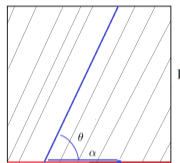
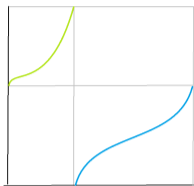
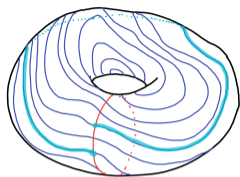


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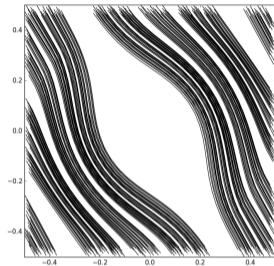
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- ▶ The **rotation number**  $\alpha$  of  $f : S^1 \rightarrow S^1$  can be defined *dynamically* ( $\alpha = \lim_{n \rightarrow \infty} \frac{f^n(x) - x}{n}$ ) or *combinatorially* (via *continued fractions* and the Euclidean algorithm).

- ▶ E.g.  $\mathcal{F}_0$  irrational *linear* foliation (angle  $\theta$ );
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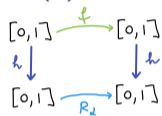
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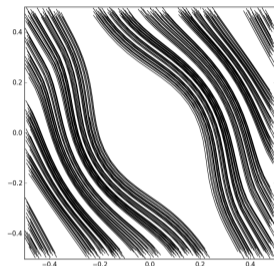
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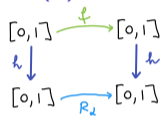
- if the rotation number  $\alpha \notin \mathbb{Q}$ ,  $\exists$  [Poincaré Thm] a topological **semi-conjugacy**, i.e. a continuous, surjective  $h : S^1 \rightarrow S^1$  such that  $h \circ f = R_\alpha \circ h$ .



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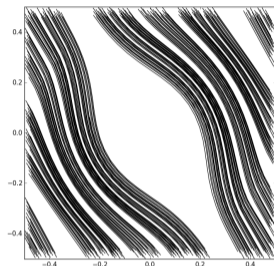
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-  $h$  could fail to be a conjugacy, if there are **wandering intervals**, i.e.  $J \subset S^1$  s.t.  $f^n(J)$ ,  $n \in \mathbb{Z}$  are all disjoint (**Denjoy counterexamples**).

[Idea:  $(f^n(J))_{n \in \mathbb{Z}}$  are obtained by *blow up* of an orbit.]



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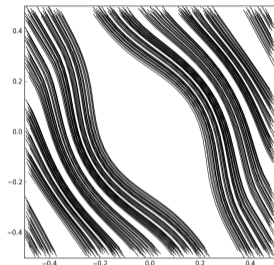
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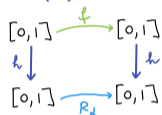
a **Denjoy** flow (courtesy of J. Carrard)

(2) **Topology**: if  $f$  is **differentiable**, e.g.  $f \in \mathcal{C}^2$  ( $\mathcal{C}^1 + f' \in BV$ ), then  $f$  is a **conjugacy**  $\Leftrightarrow$   $f$  is **minimal** [**Denjoy** theorem] (*Combinatorics (+smoothness) determines topology*).

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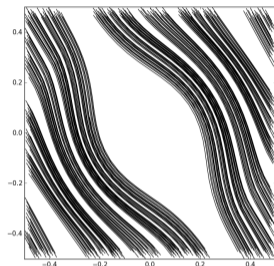
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a **Denjoy** flow (courtesy of J. Carrard)

(2) **Topology**: if  $f$  is **differentiable**, e.g.  $f \in \mathcal{C}^2$  ( $\mathcal{C}^1 + f' \in BV$ ), then  $f$  is a **conjugacy**  $\Leftrightarrow$   $f$  is **minimal** [**Denjoy** theorem] (*Combinatorics (+smoothness) determines topology*).

(3) **Geometry**: What is the regularity of  $h$ ? Is  $h \in \mathcal{C}^1$ ? Is  $h \in \mathcal{C}^\infty$ ?

(**Rigidity**: topology determines geometry)



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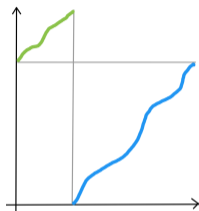
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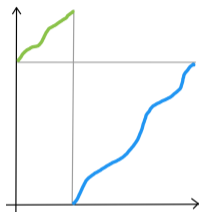


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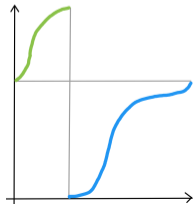
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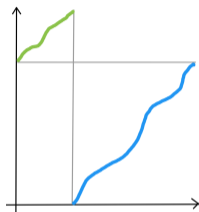


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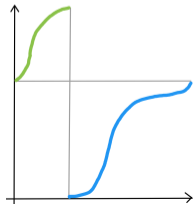
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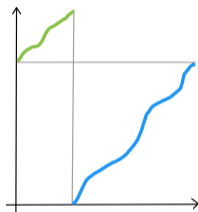
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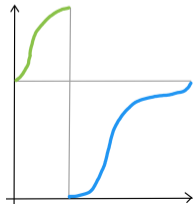
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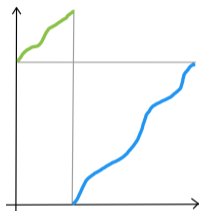
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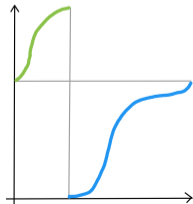
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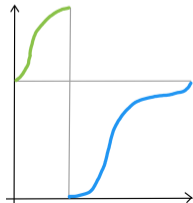
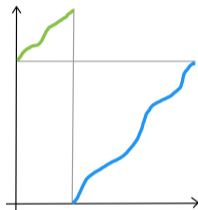
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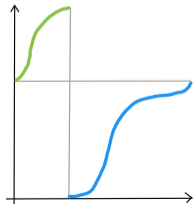
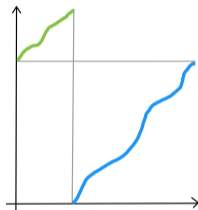
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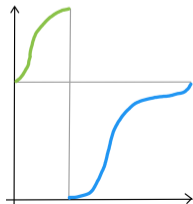
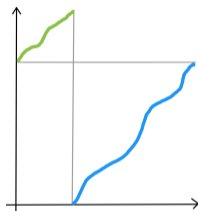
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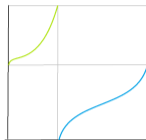
[Renormalization approach: Khanin-Sinai, Khanin-Teplinsky]



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Some examples of *geometrically rigid* dynamical systems ( $C^0 \Rightarrow C^1$  conjugacy):

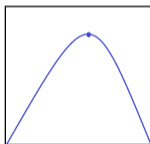
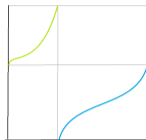
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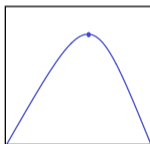
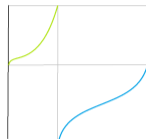
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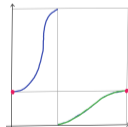
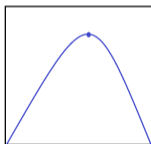
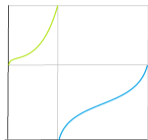
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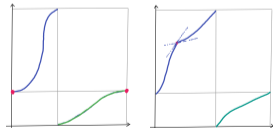
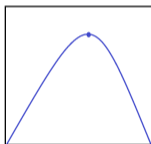
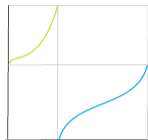
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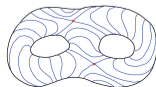
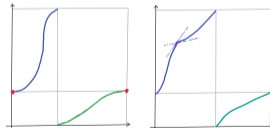
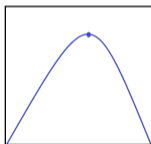
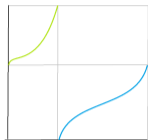
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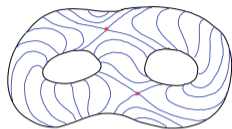
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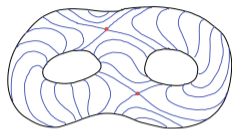
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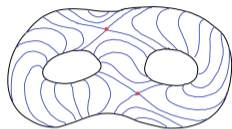


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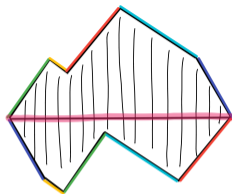


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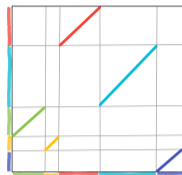
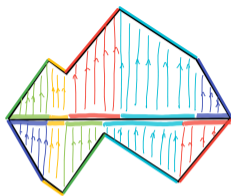
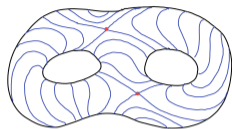


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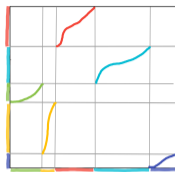
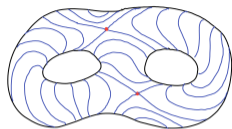


IET

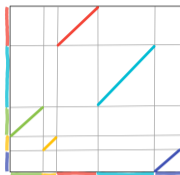
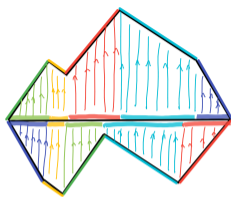
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GIET

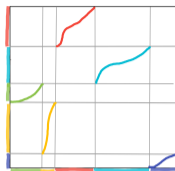
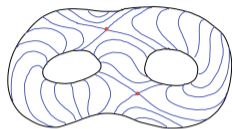


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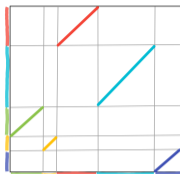
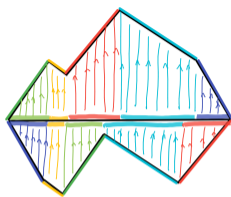
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## Poincaré maps in higher genus: generalized interval exchange maps



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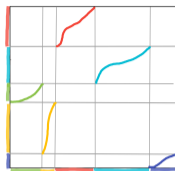
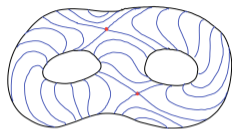


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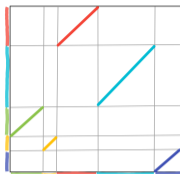
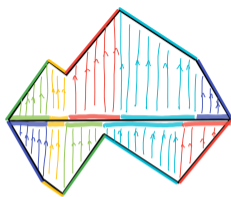
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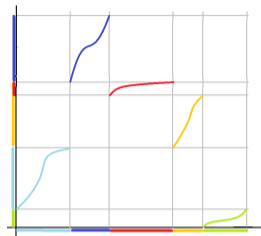
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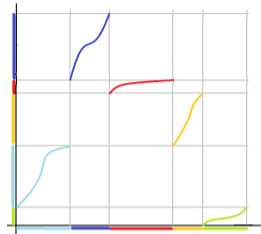


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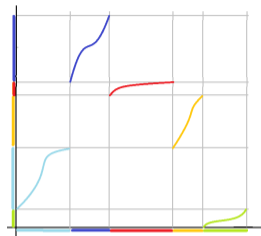


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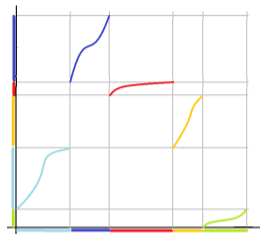


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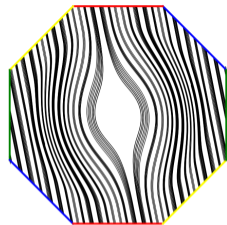
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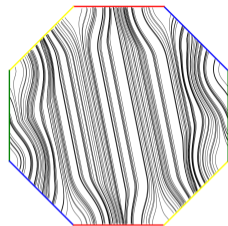
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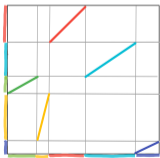
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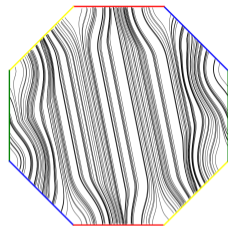
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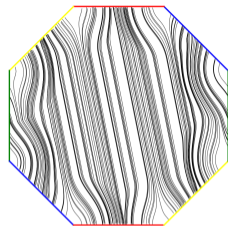
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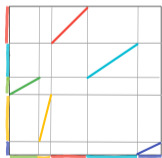
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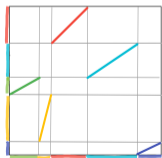
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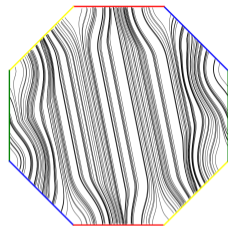
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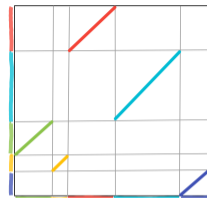
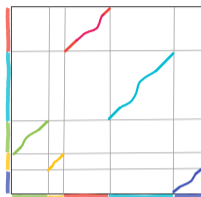
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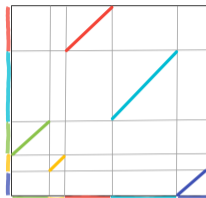
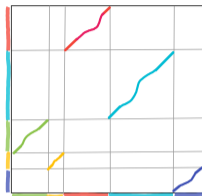


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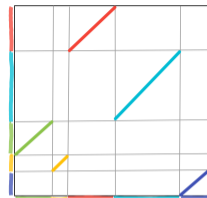
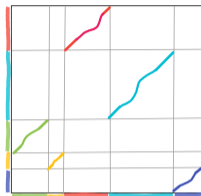
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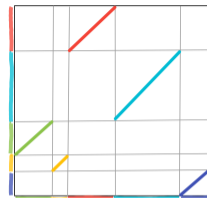
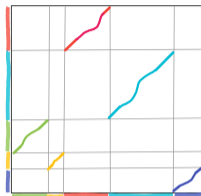
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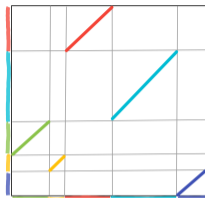
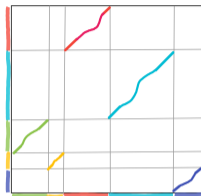
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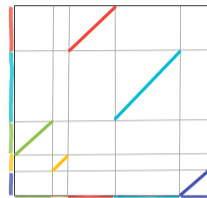
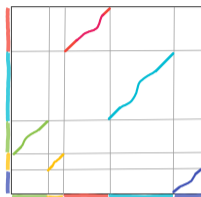
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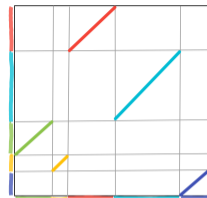
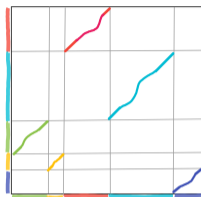
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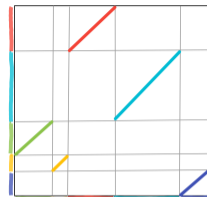
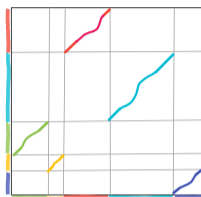
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Geometric rigidity: if  $T$  and  $T_0$  are topologically conjugate ( $h \in \mathcal{C}^0$ ), are they differentiably conjugate ( $h \in \mathcal{C}^1$ )?

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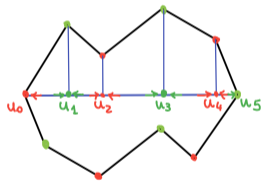
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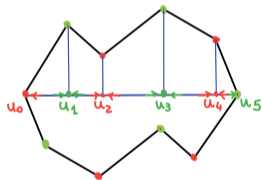


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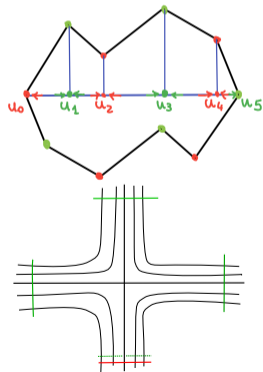


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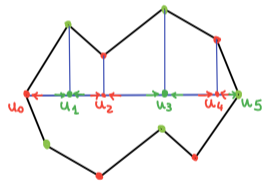


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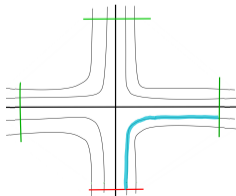
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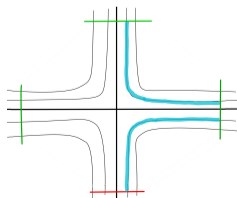
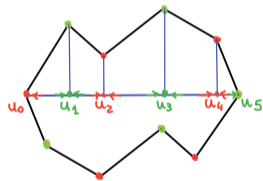
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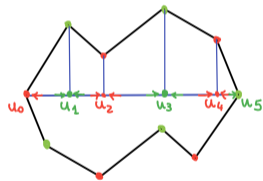


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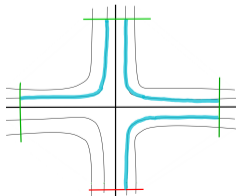
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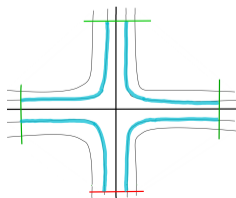
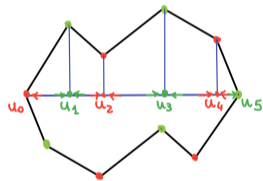




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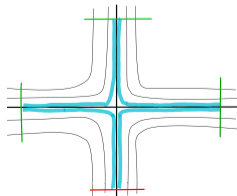
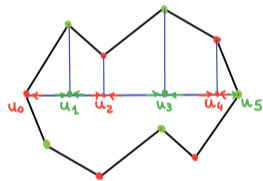


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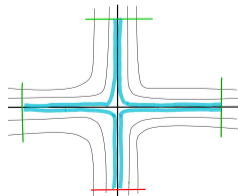
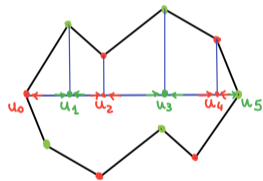


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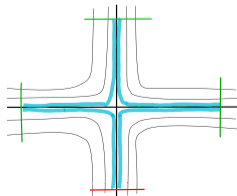
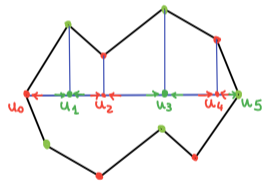


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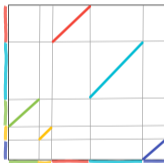
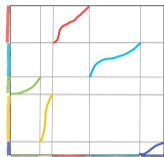
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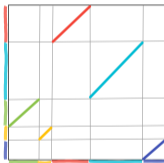
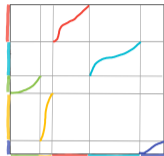
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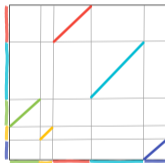
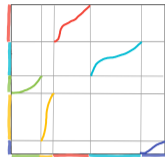
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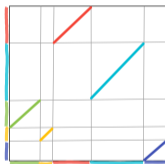
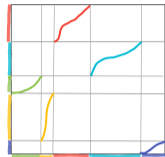
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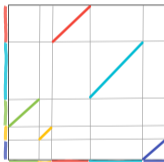
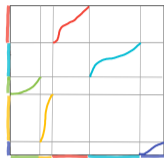
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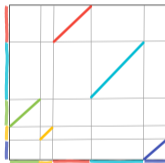
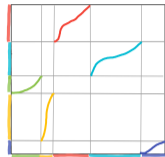
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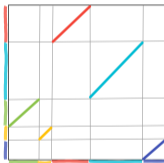
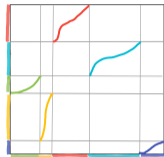
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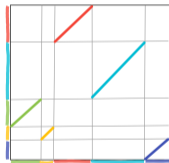
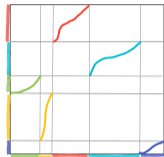
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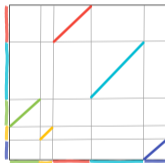
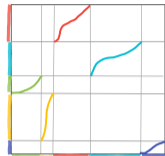
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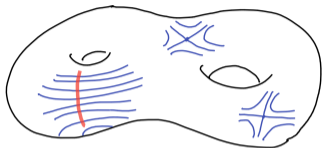
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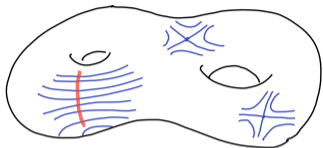
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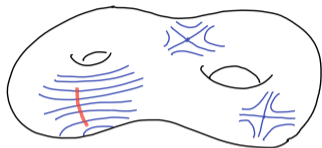


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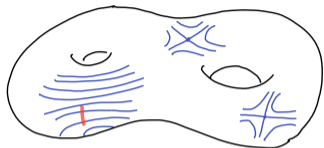
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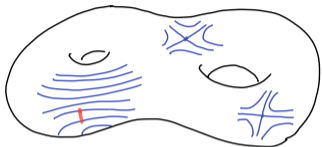
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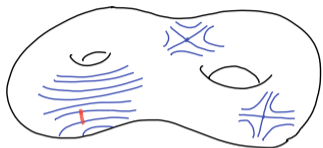
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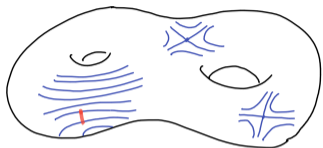


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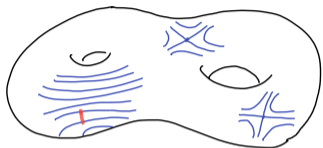


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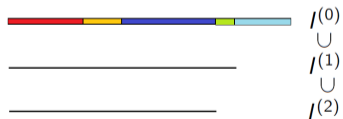


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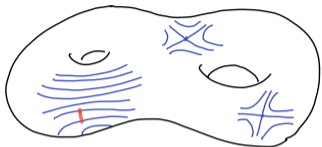


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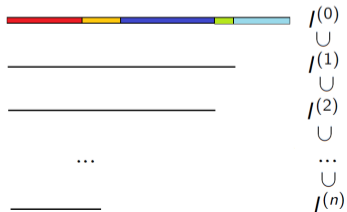


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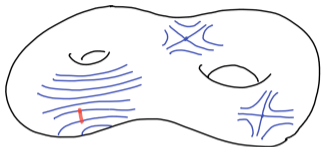


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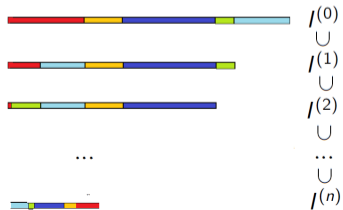


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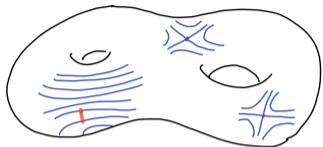




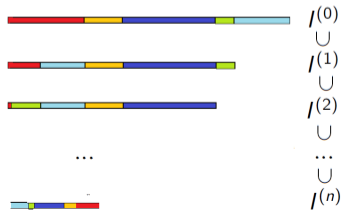
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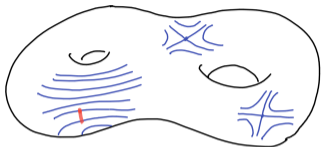


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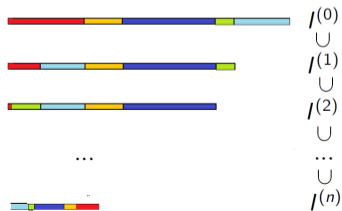
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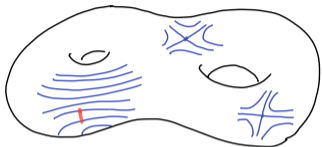
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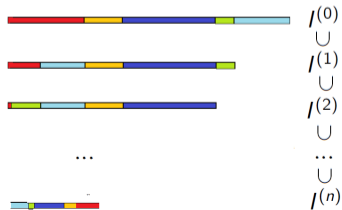
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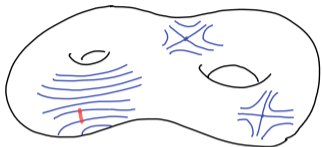
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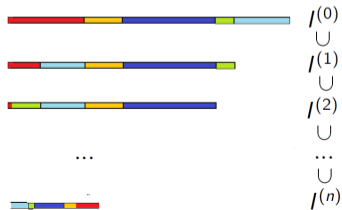


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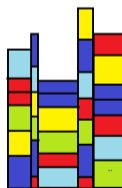


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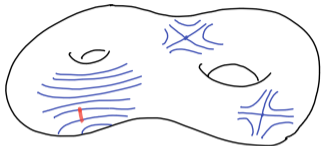
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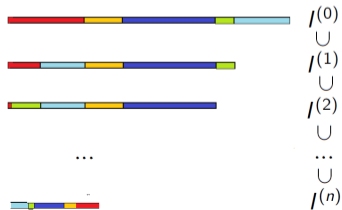


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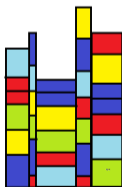


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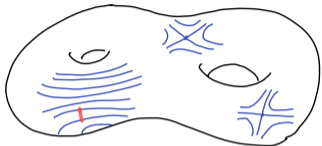
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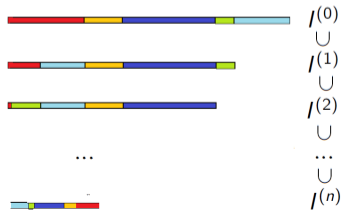


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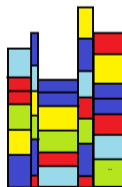


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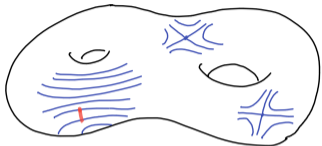
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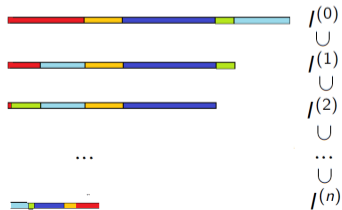


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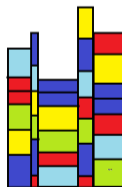


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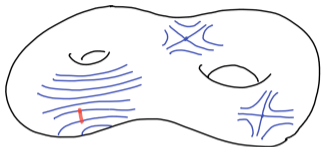
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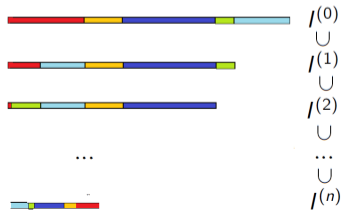


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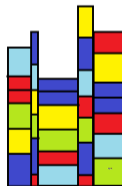


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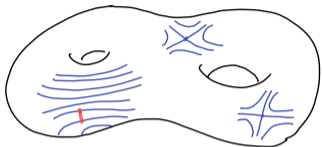
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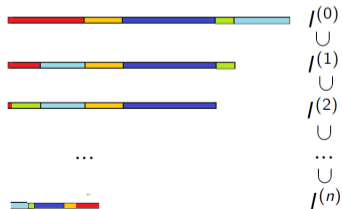


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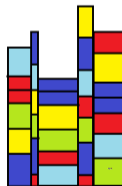


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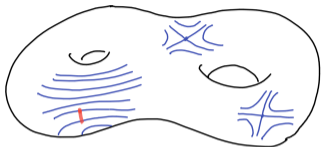
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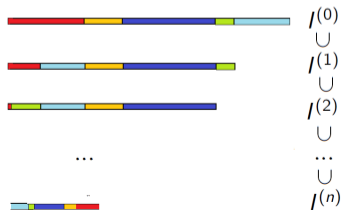
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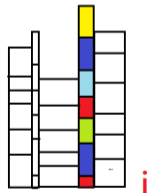


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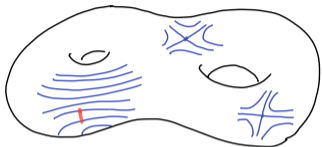
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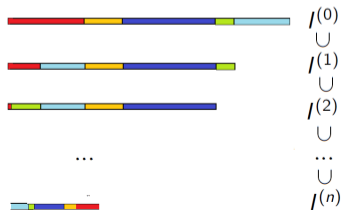
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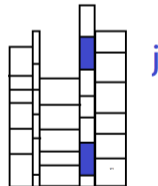


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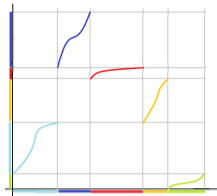
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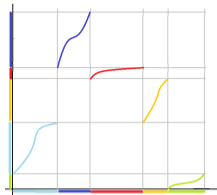
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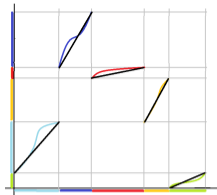
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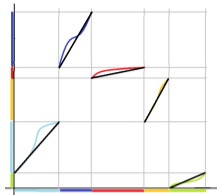
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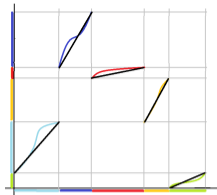
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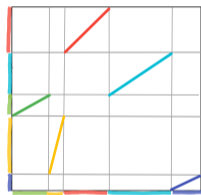
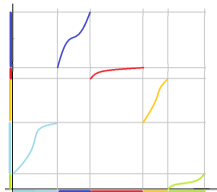
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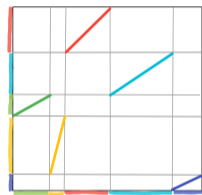
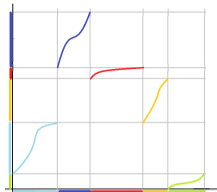
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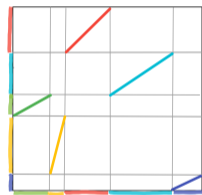
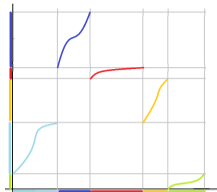
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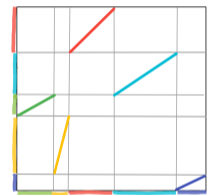
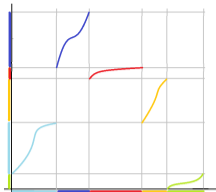
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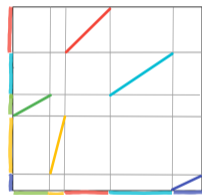
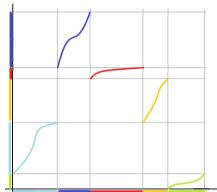
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## Strategy to prove rigidity ( $\mathcal{C}^0 \Rightarrow \mathcal{C}^1$ )

Assume that  $T$  is such that the dynamical dichotomy holds. Consider two cases:

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- ▶  $\frac{1}{\nu} \leq \rho^{(n_k)} \leq \nu$  (a priori bounds);
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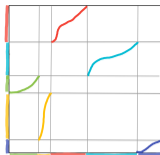
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1. Show a priori bounds at  $(n_k)_k$  [i.e.  $\frac{1}{C} \leq DT^{(n)} \leq C$ ];

- ▶ Consider separately *shape* and *profile* coordinates:
  - ▶ the *shape* is the *affine* IET with log-slope  $\omega_n$ ;
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2. Convergence to Moebius IET: no  $B$  assumption!

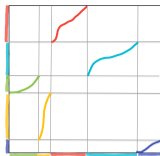
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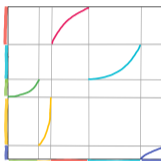
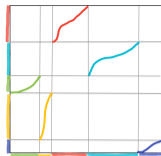
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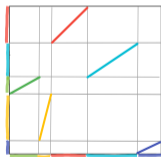
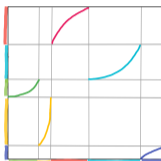
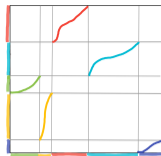
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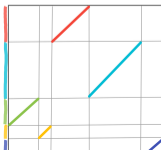
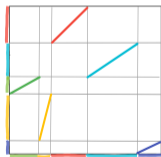
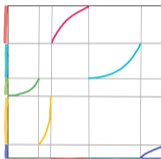
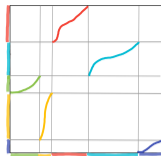
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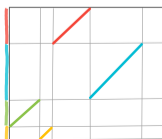
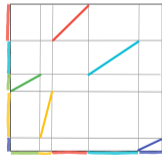
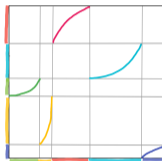
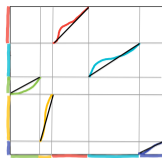
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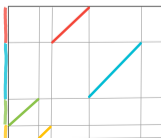
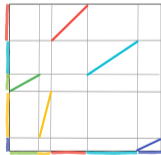
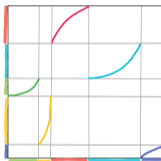
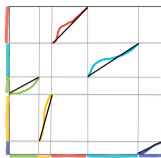
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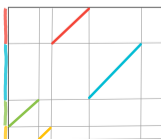
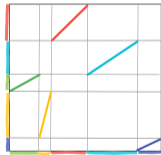
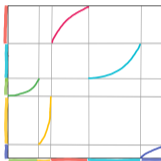
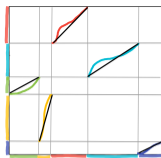
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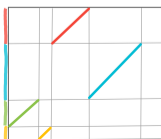
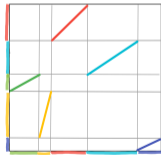
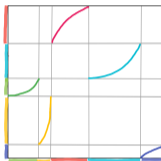
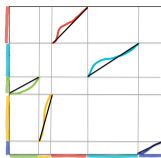
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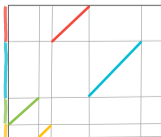
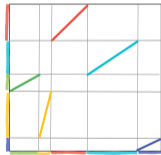
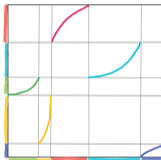
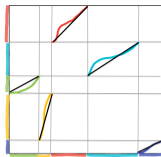
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- ▶ *Example*: periodic type case, i.e.  $B(0, np) = A^n$ , for any  $n$ , where  $A > 0$ ;
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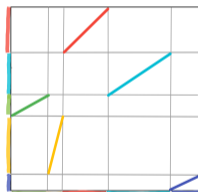
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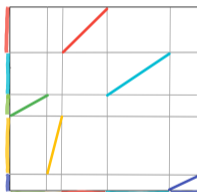
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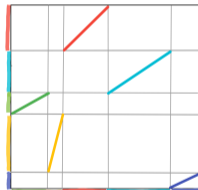
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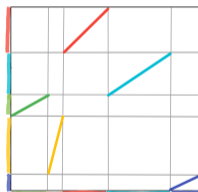
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$\gamma(T_0)$  satisfy the (RDC) if there exists a *linearly growing* sequence  $(n_k)_{k \in \mathbb{N}}$  of *effective Oseledets* times such that:

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Condition on the rotation number  $\gamma(T) = \gamma(T_0)$  (valid for **full measure** set of IET  $T_0$ ):

- ▶ Assume  $T$  is *Oseledets generic*; consider an *effective Oseledets* acceleration  $\mathcal{R}$ ;
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$\gamma(T_0)$  satisfy the (RDC) if there exists a *linearly growing* sequence  $(n_k)_{k \in \mathbb{N}}$  of **effective Oseledets** times such that:

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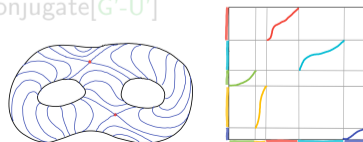
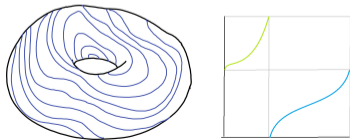
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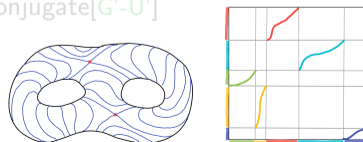
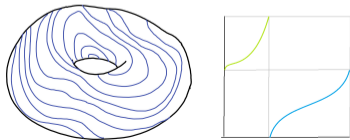
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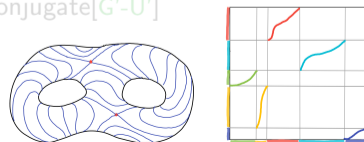
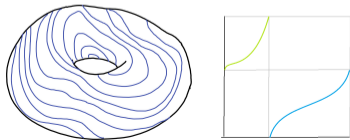
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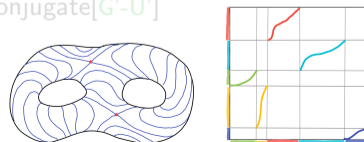
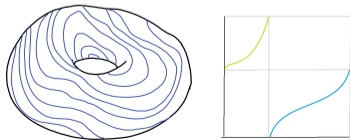
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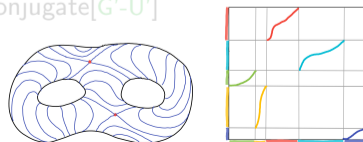
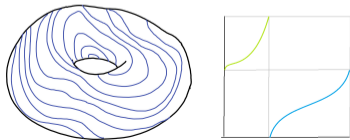
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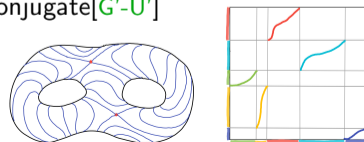
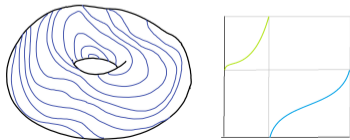
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## Extra: Wandering intervals and distorted towers

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For a.e.  $T$ , if  $T_0$  is an affine IET such that:

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then  $T$  has wandering intervals.

To show: the result also holds for every  $\nu$  s.t.  $\frac{\log \|B(0,n)\nu\|}{n} = \theta_i > 0$ .

To show this, [MMY] prove that for a sequence  $(n_\ell)_\ell$ , the partitions  $\mathcal{P}_{n_\ell}$  are exponentially distorted, i.e. for every  $j$  there exists a floor of the  $j$ -tower s.t.

$$|T^i F_0| = |T^{k_0+i} I_j^{(n)}| \leq C \exp(-c|i|^\gamma) |F_0|.$$

In particular, for every  $1 \leq j \leq d$

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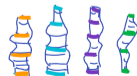
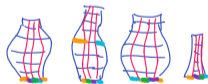
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E.g.: uses of the *double occurrence*  $AA$  of a positive matrix  $A > 0$ .

Proposition:  $\text{mesh}(\mathcal{P}_{n_k}) \leq C\nu^k$  for  $\nu < 1$  (i.e. the mesh decay exponentially), where:

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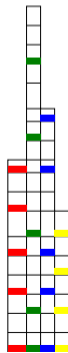
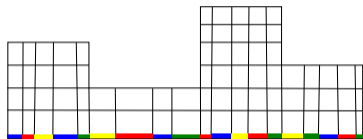
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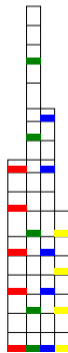
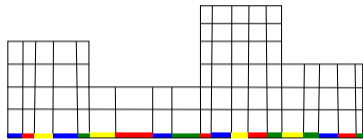


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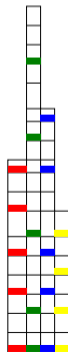
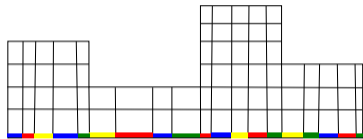


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  - ▶ Matrix  $A$  after  $n_1 \Rightarrow$  base intervals are *comparable*;
  - ▶ Matrix  $A$  before  $n_1 +$  a priori bounds  $\Rightarrow$  floors above  $n_1$  are all *comparable*
  - ▶ *Distorsion bounds*  $\Rightarrow$  ratios are preserved within each tower;
- ▶ Conclude that between  $n_0$  and  $n_1$  the mesh drops by a constant factor.

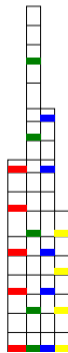
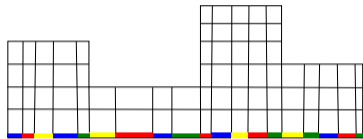


## Extra: exponential decay of the dynamical partitions mesh

E.g.: uses of the *double occurrence*  $AA$  of a positive matrix  $A > 0$ .

**Proposition:**  $\text{mesh}(\mathcal{P}_{n_k}) \leq C\nu^k$  for  $\nu < 1$  (i.e. the mesh *decay exponentially*), where:

- ▶  $\mathcal{P}_n$  denotes the  $n^{\text{th}}$  dynamical partition;
- ▶  $\text{mesh}(\mathcal{P}) :=$  is the length of largest interval;
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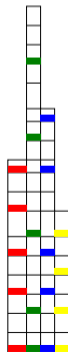
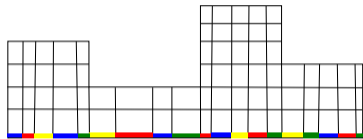


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## Extra: Effective Oseledets estimates

Given  $T$ , let  $\hat{T}$  an *Oseledets generic extension*, so that we have *splittings*:

$$\mathbb{R}^d = E_s^{(n)} \oplus E_c^{(n)} \oplus E_u^{(n)}, \quad \forall n \in \mathbb{N}.$$

### Definition (Effective Oseledets sequence)

A sequence  $(k_m)_{m \in \mathbb{N}}$  is an *effective Oseledets sequence* if for  $s, C_1 > 0, \theta > 0, \epsilon > 0, c_2(\epsilon) > 0$  we have:

$$\|B(n_k, n)|_{E_s^{(n_k)}}\|_\infty \leq C_1 e^{-\theta(n-n_k)} \quad \text{for every } n \geq n_k, \quad (\text{EO1})$$

$$\|B(n, n_k)^{-1}|_{E_u^{(n_k)}}\|_\infty \leq C_1 e^{-\theta(n_k-n)} \quad \text{for every } n \leq n_k, \quad (\text{EO2})$$

$$|\angle(E_x^{(n)}, E_y^{(n)})| \geq c_2 e^{-\epsilon|n-n_k|}, \quad \text{for all } n \in \mathbb{Z}, \text{ distinct } x, y \in \{s, c, u\}; \quad (\text{EO3})$$

$$\lim_{k \rightarrow +\infty} \frac{\log \|B(n_k, n_{k+1})\|}{k} = 0. \quad (\text{EO4})$$