



Optimal Scheduling of **Real Time** traffic in Wireless Networks with **Delayed Feedback**

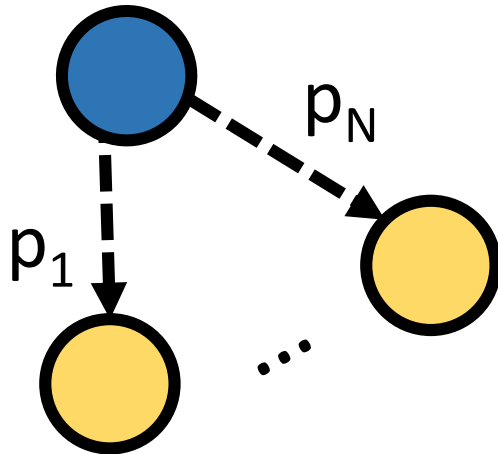
Kyu Seob Kim, Chih-Ping Li, **Igor Kadota** and Eytan Modiano

Allerton Conference, October 1, 2015

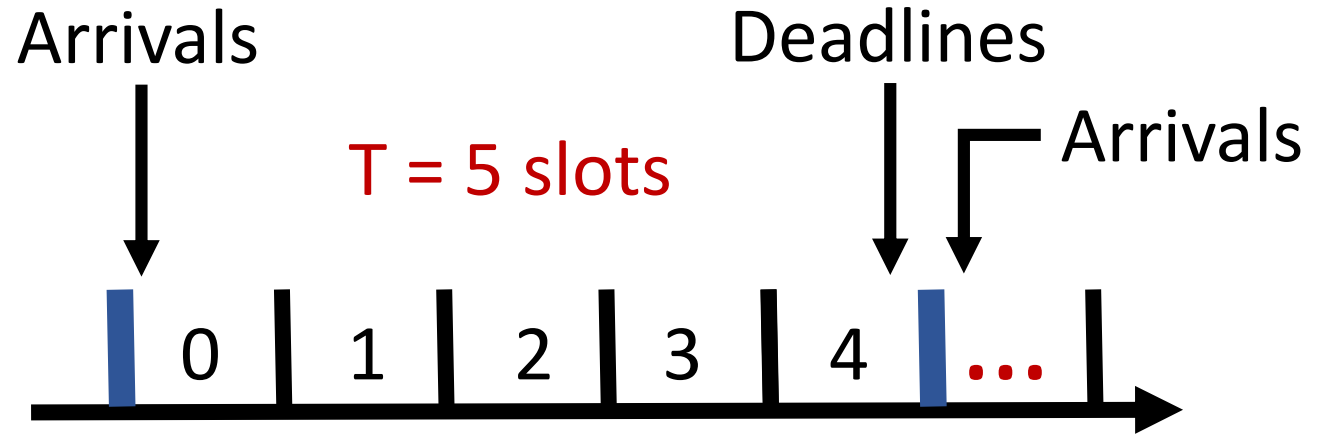
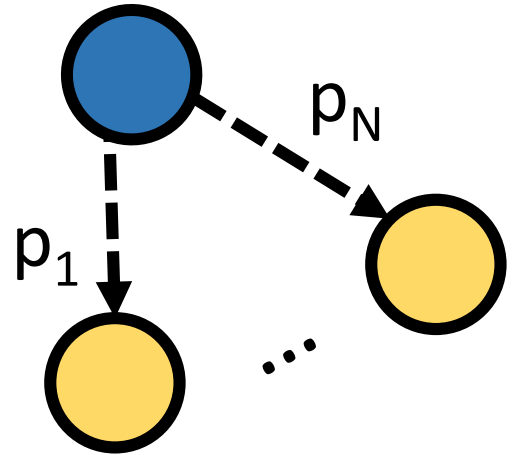
Contributions / Topics

- Network Model
- DP Solution
- Feasible Region
- Feasibility Optimal Dynamic Algorithm
- Low-complexity Heuristic Algorithm

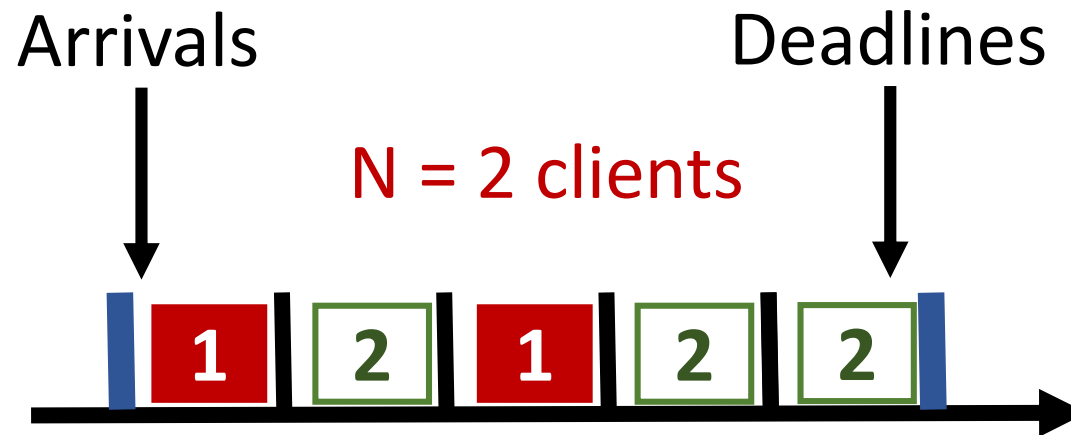
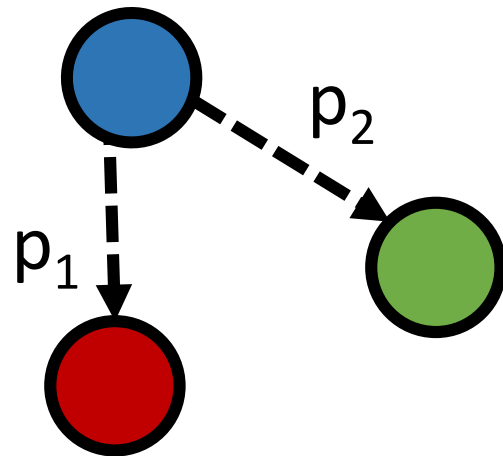
Wireless Single-Hop Network



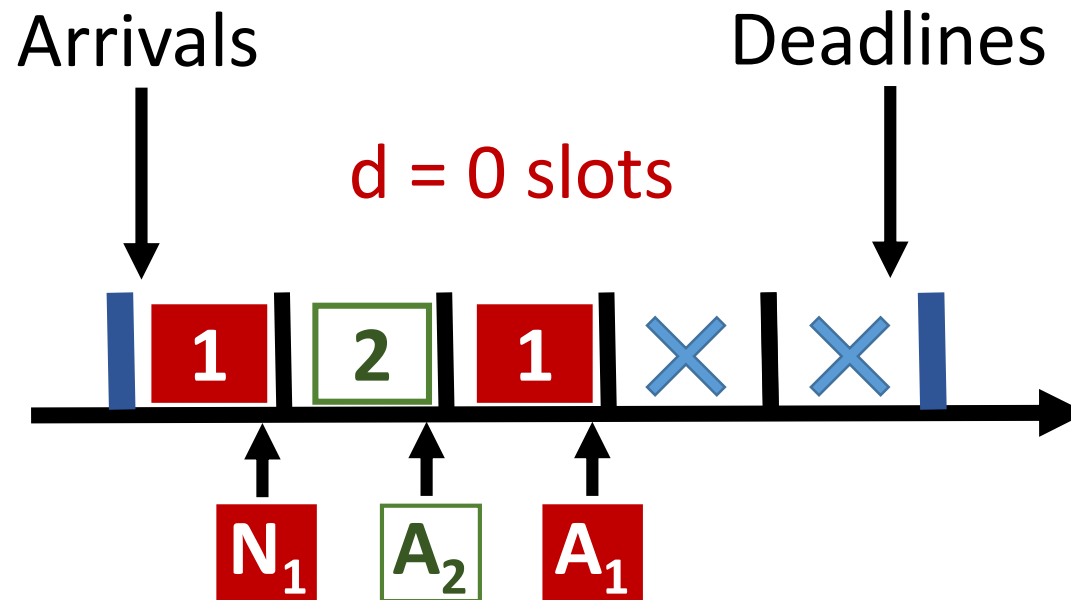
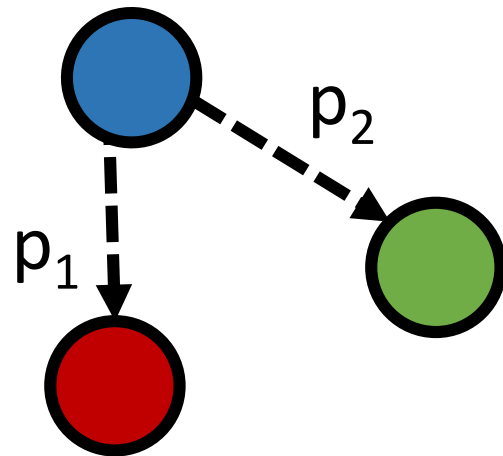
Wireless Single-Hop Network



Wireless Single-Hop Network

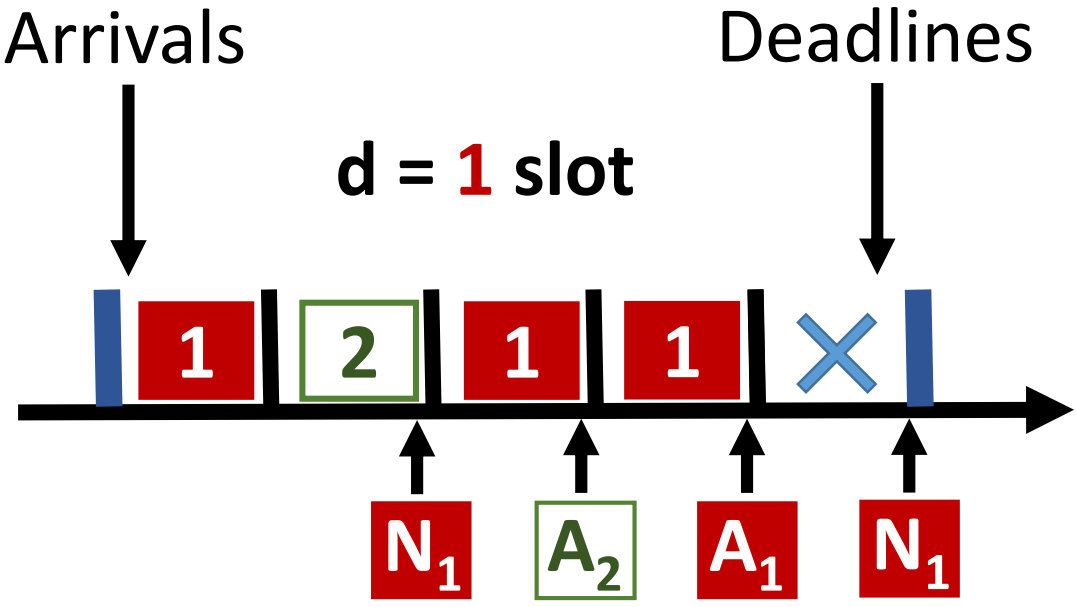
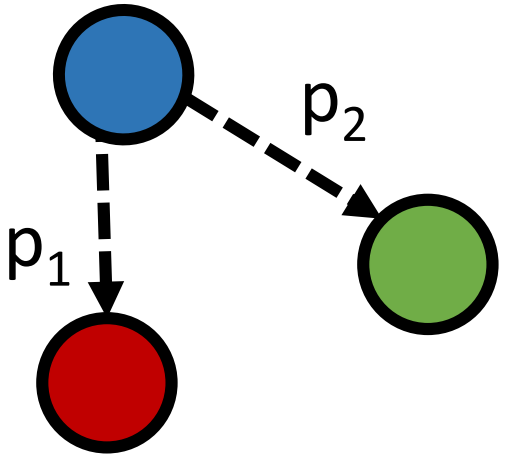


Wireless Single-Hop Network



[6] I-Hong, Kumar, **var.-bit-rate**, 2009.
 [7] I-Hong, Kumar, **fading channels**, 2010.
 [8] Kyu, Chih-Ping, Eytan, **multicast**, 2014.

Delayed Feedback



QoS Requirements and Goal

- $\eta \in \Pi$
- $D_i^\eta(k) = 1$ or 0

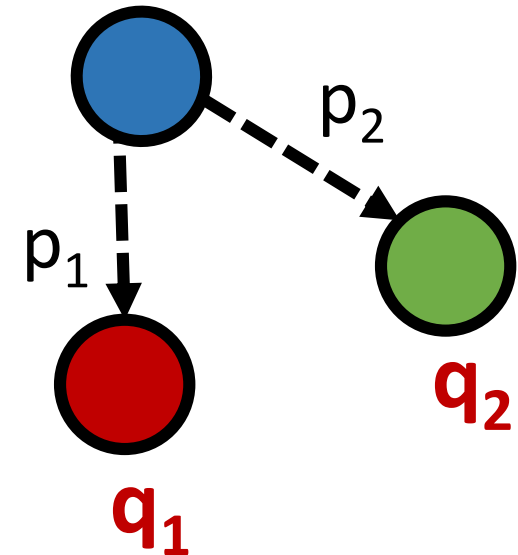
Throughput “i”:

$$\hat{q}_i^\eta \triangleq \liminf_{K \rightarrow \infty} \frac{1}{K} \sum_{k=0}^{K-1} D_i^\eta(k)$$

QoS Requirements:

$$P(\hat{q}_i^\eta \geq q_i) = 1, \forall i$$

Goal is to find $\eta \rightarrow$ EWST (Expected Weighted Sum Throughput)

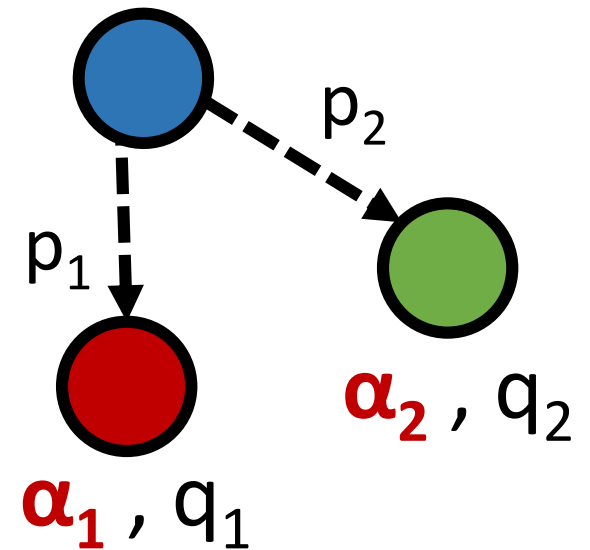


QoS Requirements and Goal

- $\eta \in \Pi$
- $D_i^\eta(k) = 1$ or 0

Optimization Problem:

$$EWST(\vec{\alpha}) = \max_{\eta \in \Pi} \sum_{i=1}^N \alpha_i E[D_i^\eta(0)]$$



Dynamic Program

For t and for \tilde{s}_t :

$$J_t(\tilde{s}_t) = \max_{u_t \in U_t(\cdot)} E[g_t(\cdot) + J_{t+1}(\cdot)]$$

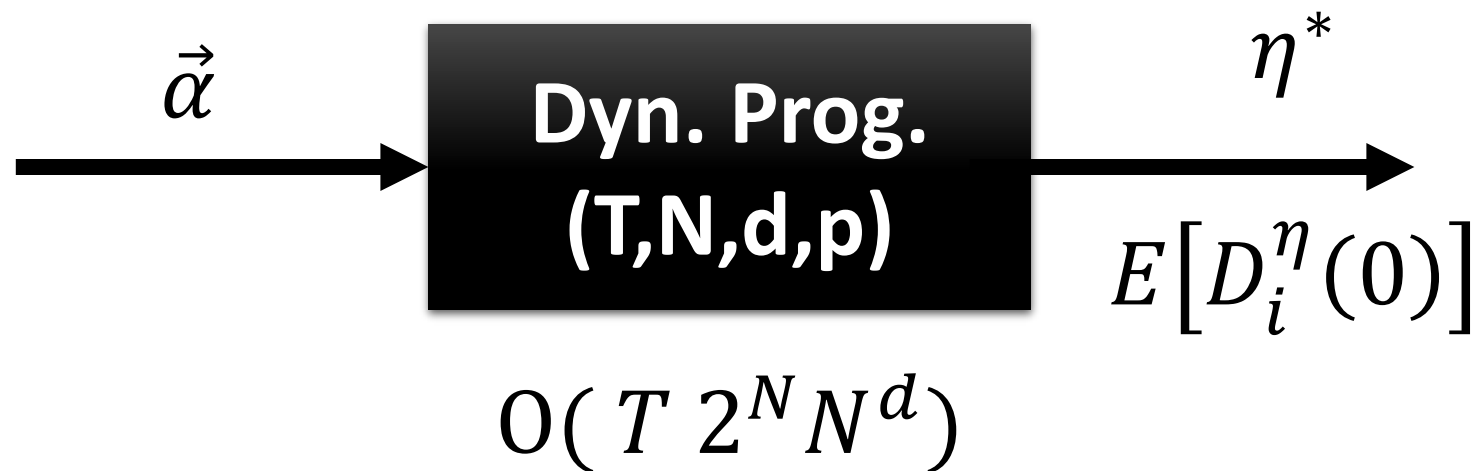
Result:

$$J_0(\emptyset) = \max_{\eta \in \Pi} \sum_{i=1}^N \alpha_i E[D_i^\eta(0)] \quad \text{and} \quad \eta^*$$

Dynamic Program

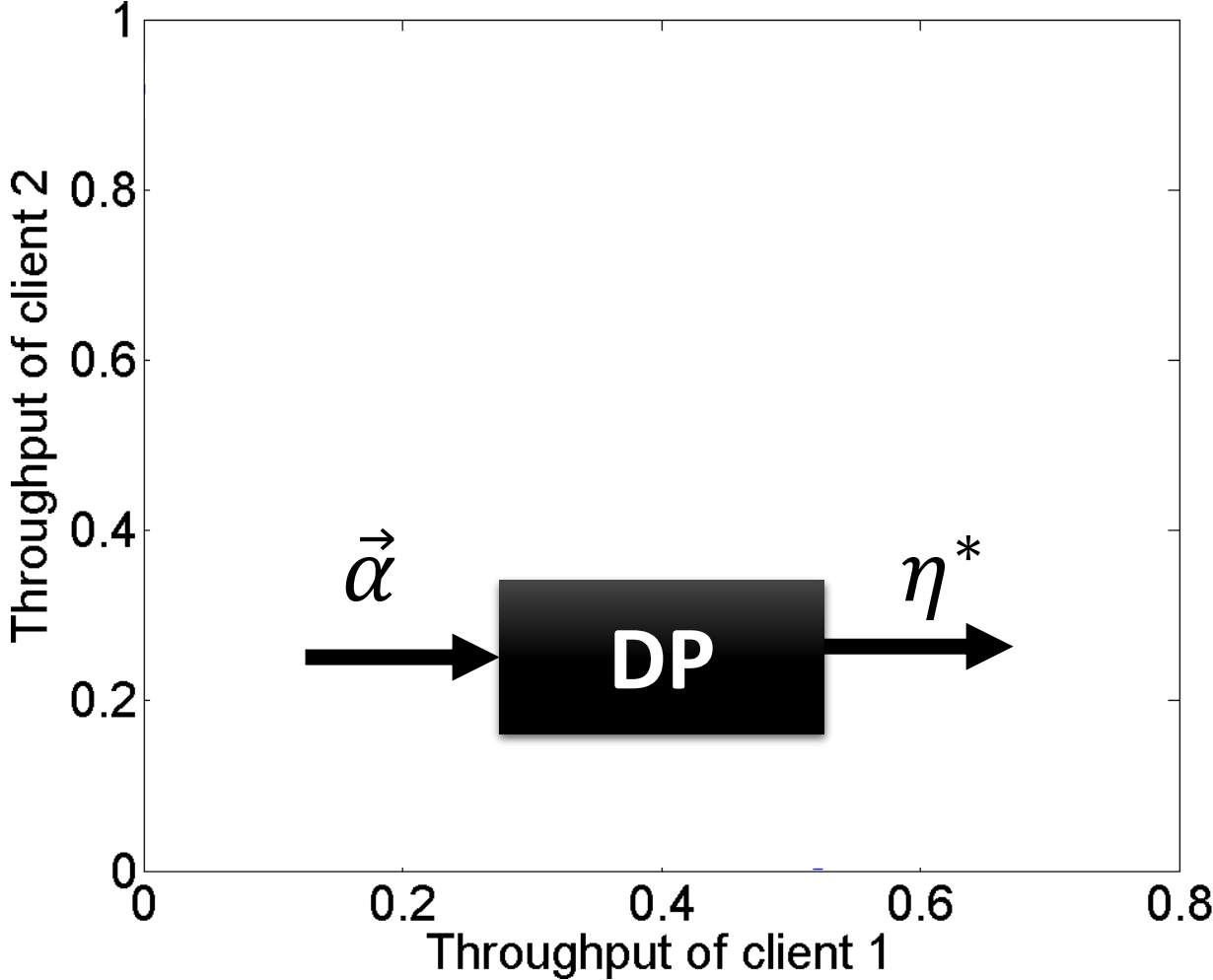
For t and for \tilde{s}_t :

$$J_t(\tilde{s}_t) = \max_{u_t \in U_t(\cdot)} E[g_t(\cdot) + J_{t+1}(\cdot)]$$

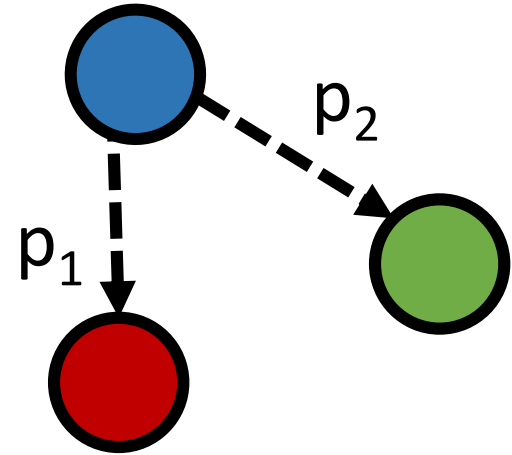


Feasible
Region

Feasible Throughput Region

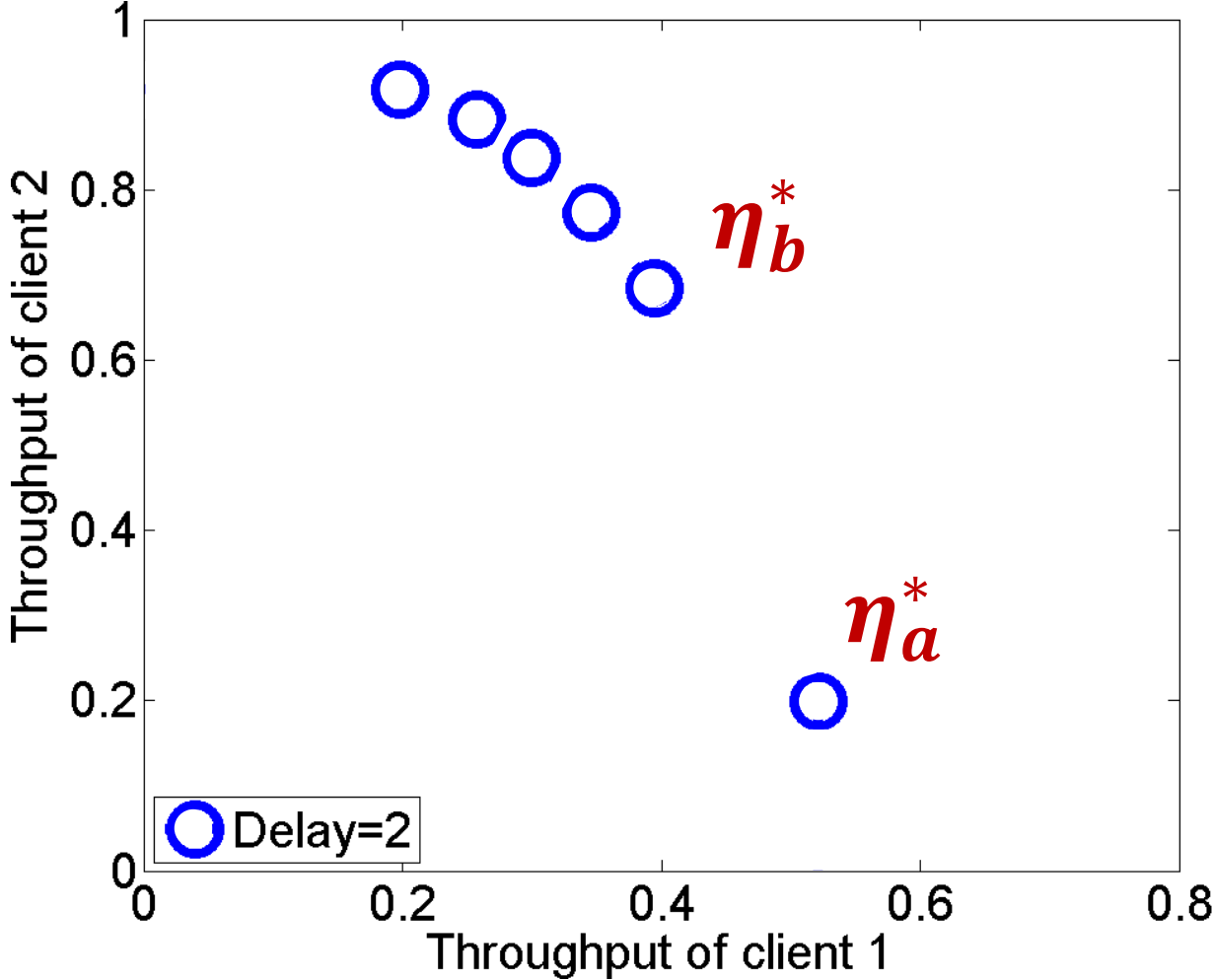


$N = 2$
 $T = 7$
 $d = 2$
 $p_1 = 0.1$
 $p_2 = 0.3$

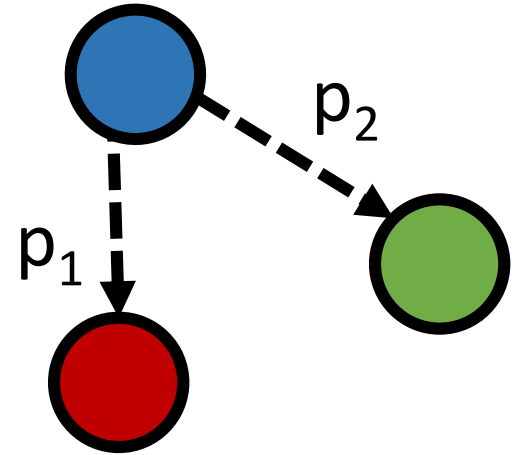


Feasible
Region

Feasible Throughput Region

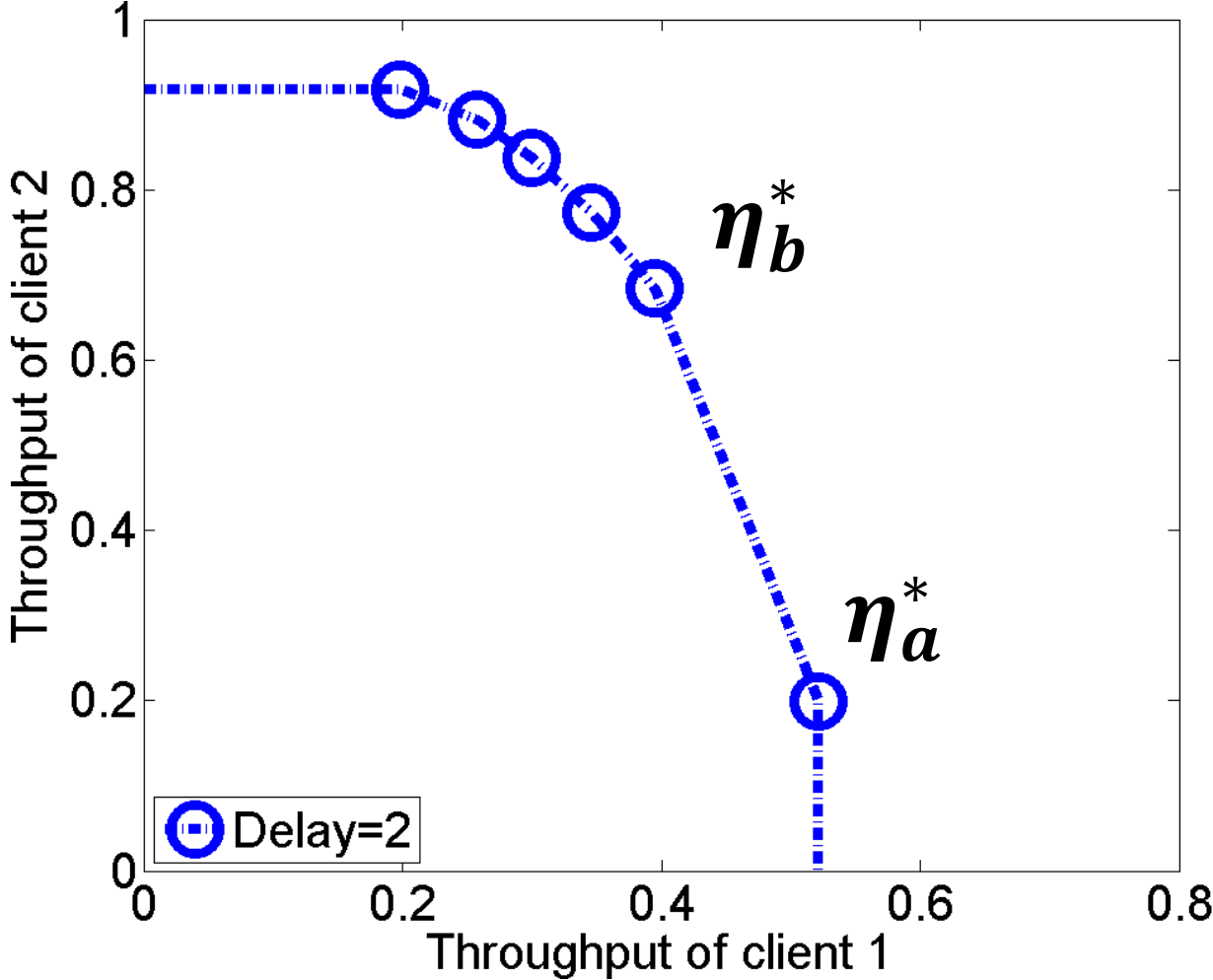


$N = 2$
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 $d = 2$
 $p_1 = 0.1$
 $p_2 = 0.3$

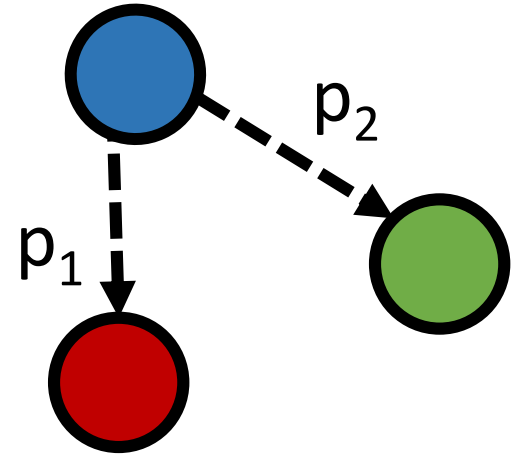


Feasible
Region

Feasible Throughput Region

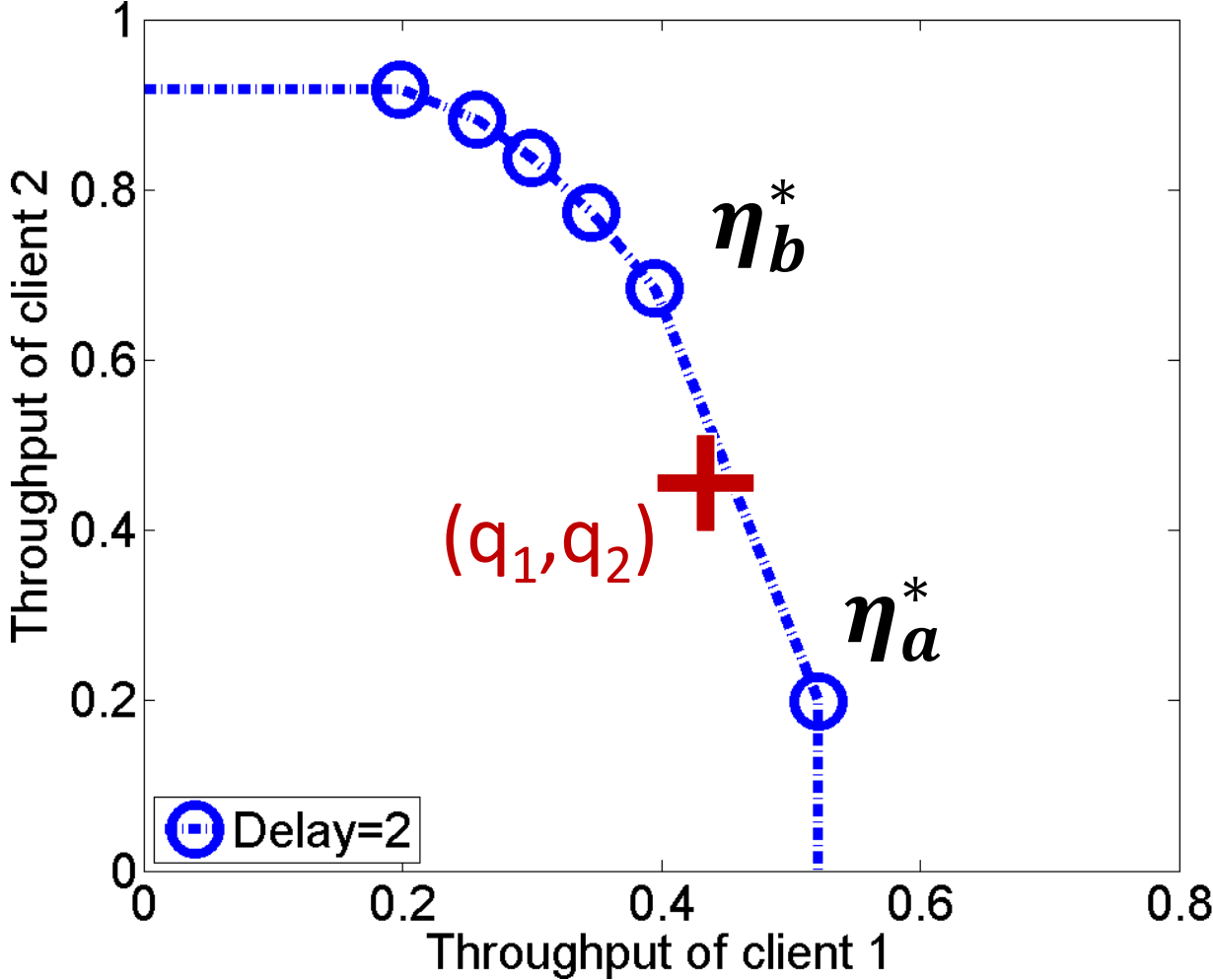


$N = 2$
 $T = 7$
 $d = 2$
 $p_1 = 0.1$
 $p_2 = 0.3$

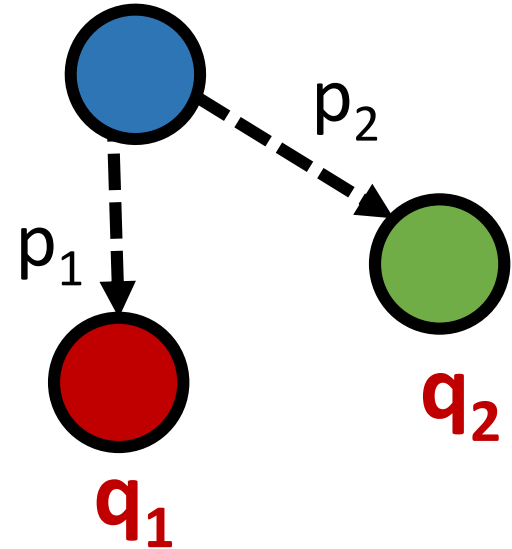


Feasible
Region

Feasible Throughput Region



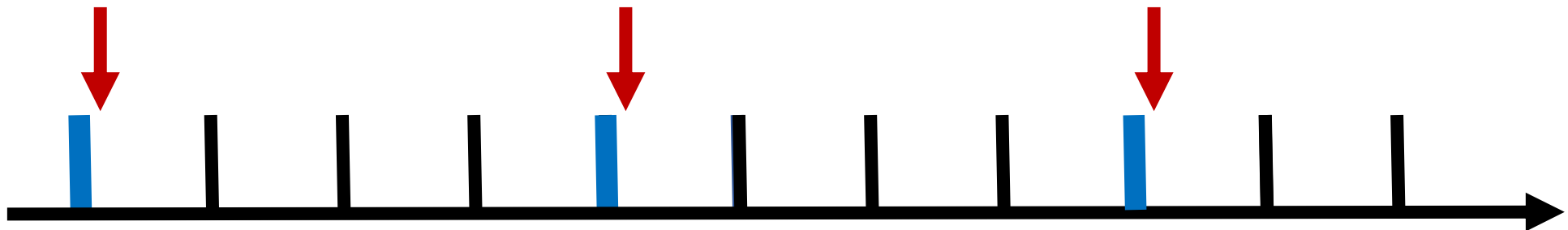
$N = 2$
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 $p_1 = 0.1$
 $p_2 = 0.3$



Feasibility Optimal Algorithm

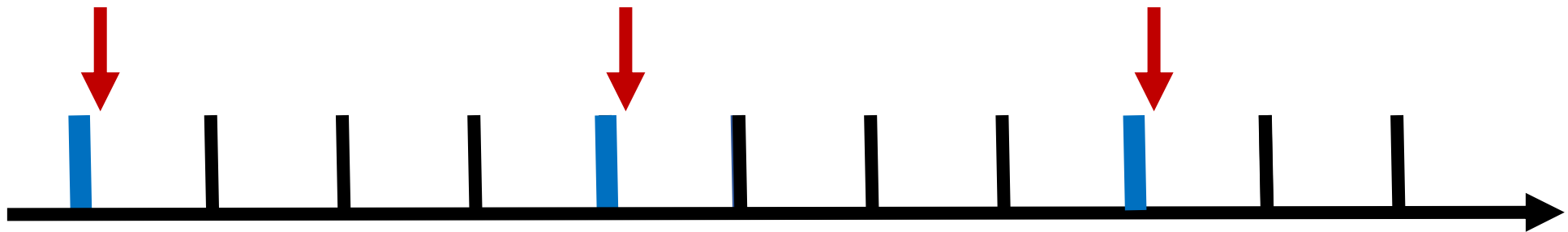
$$d_i(k) = kq_i - Q_i(k)$$

frame k

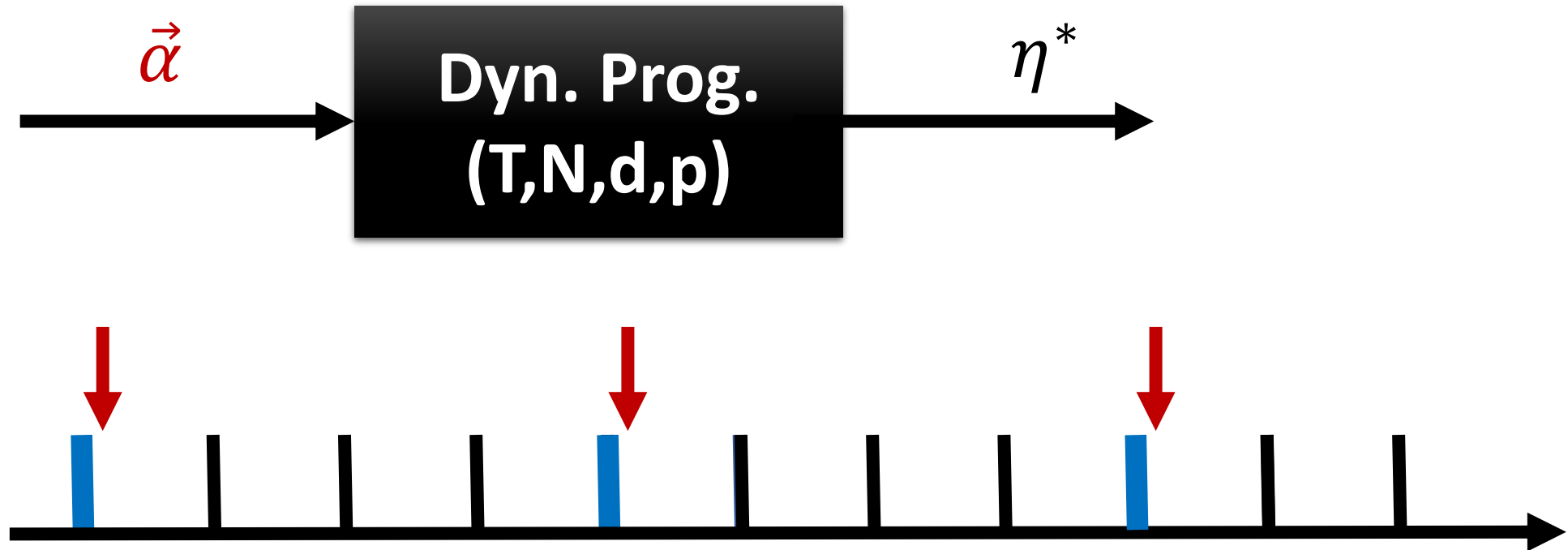


Feasibility Optimal Algorithm

$$\alpha_i = \max\{d_i(k), 0\} \rightarrow \vec{\alpha}$$



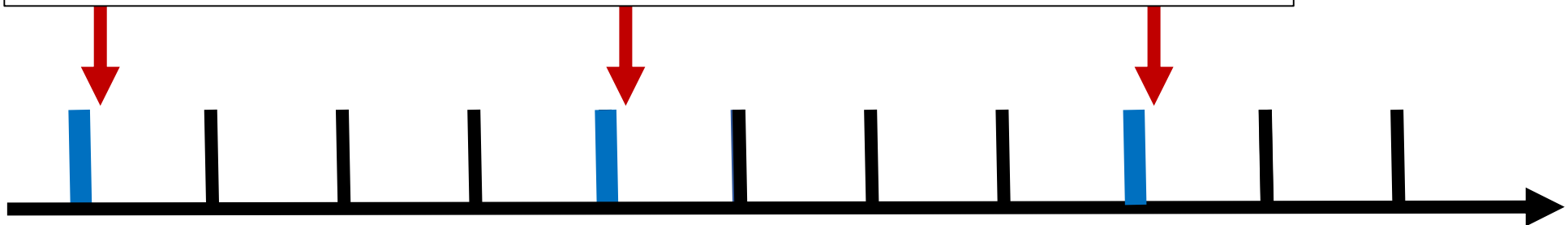
Feasibility Optimal Algorithm



Feasibility Optimal Algorithm

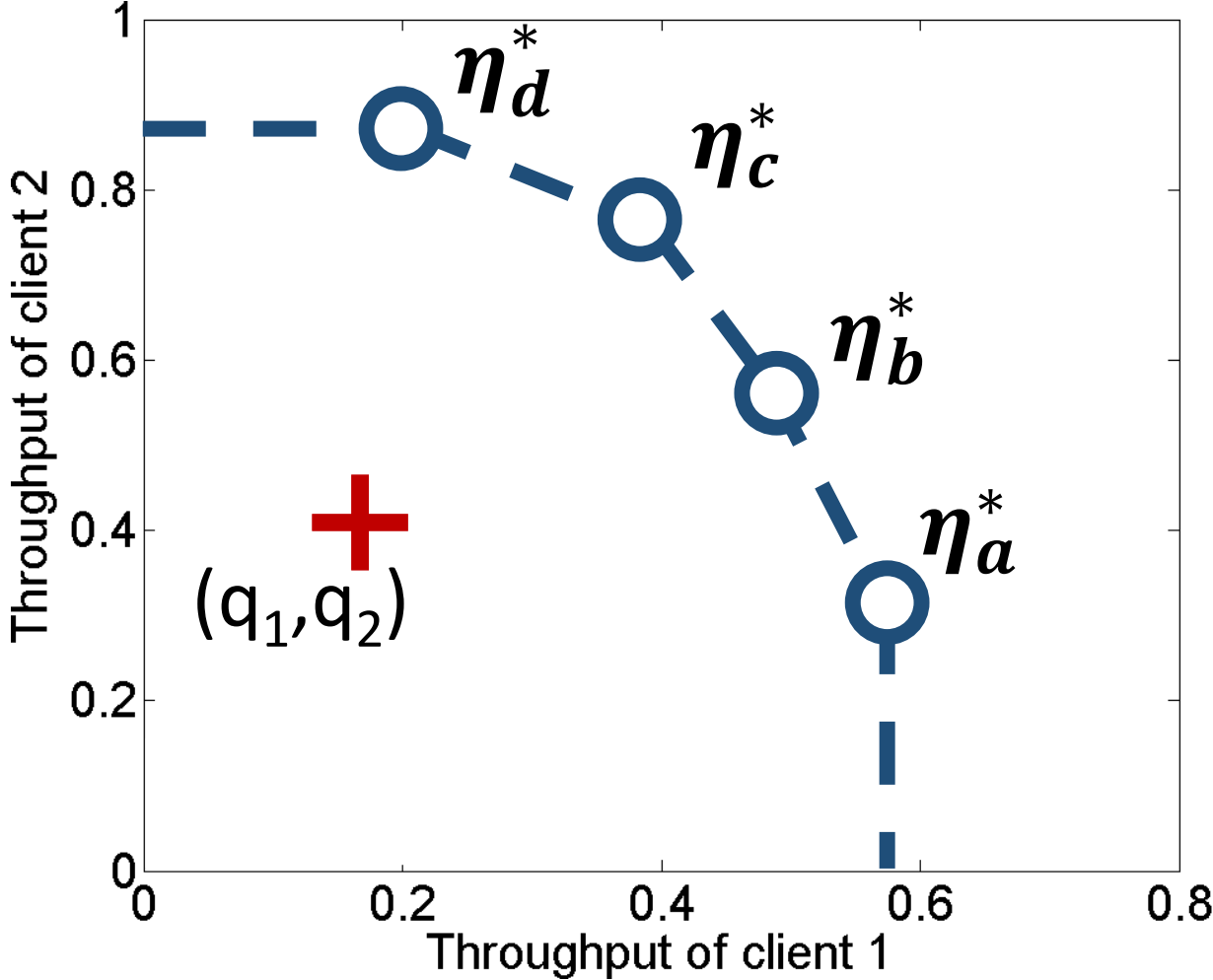
Frame-Based Max-Weight Algorithm

- $d_i(k) = kq_i - Q_i(k)$
- $\alpha_i = \max\{d_i(k), 0\}$
- Employ η^*

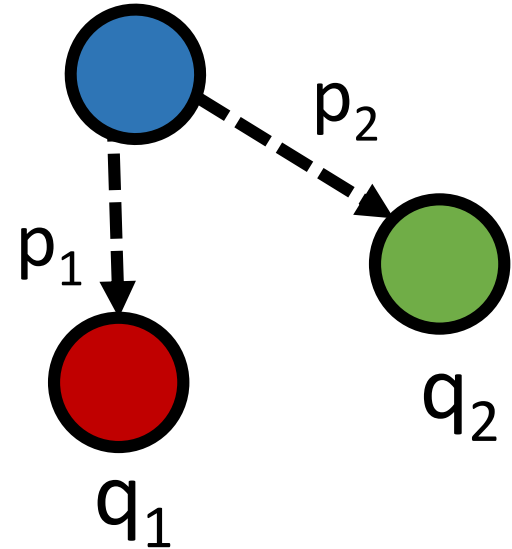


Optimal Algorithm

Feasibility Optimal Algorithm

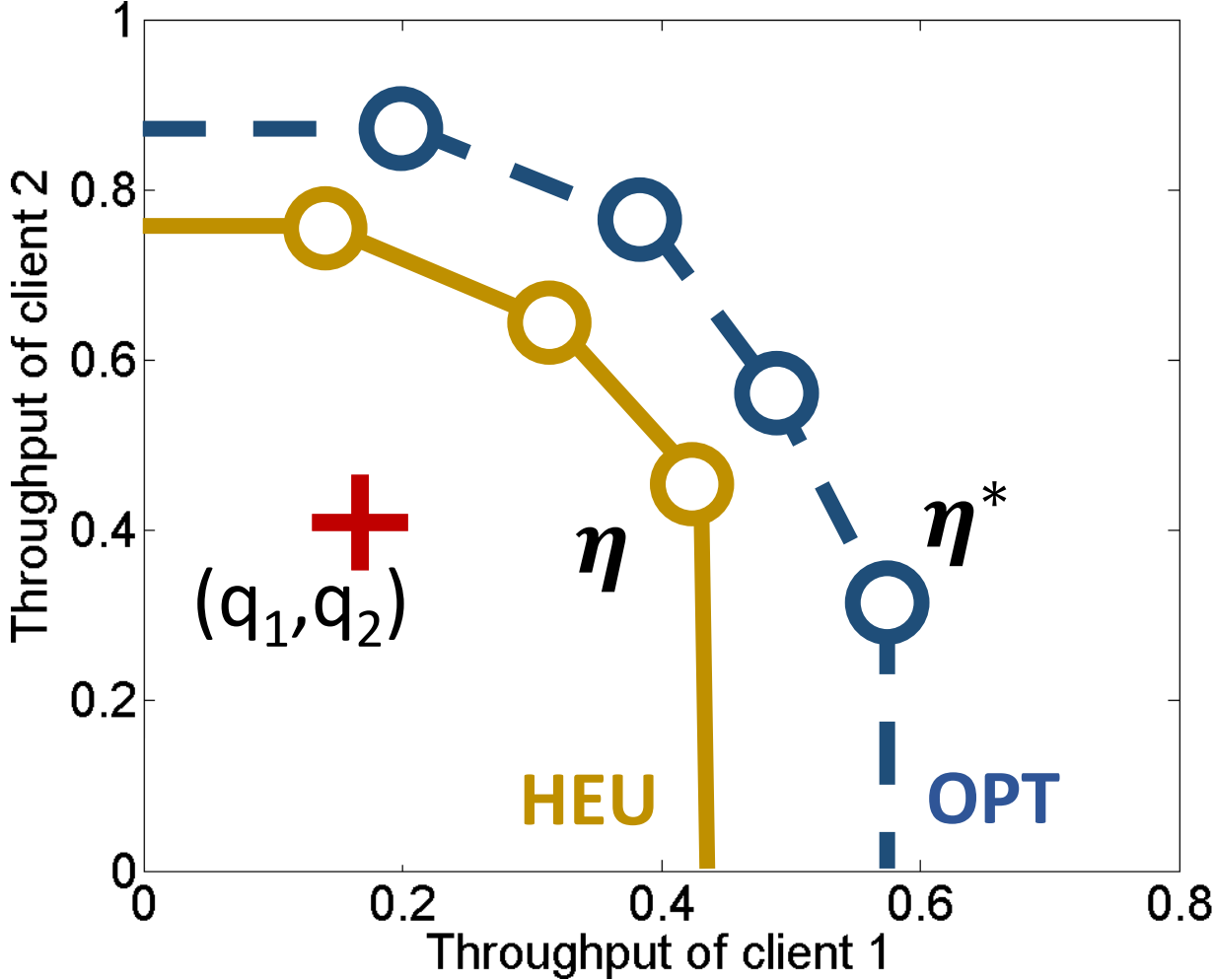


N
T
d
p₁
p₂

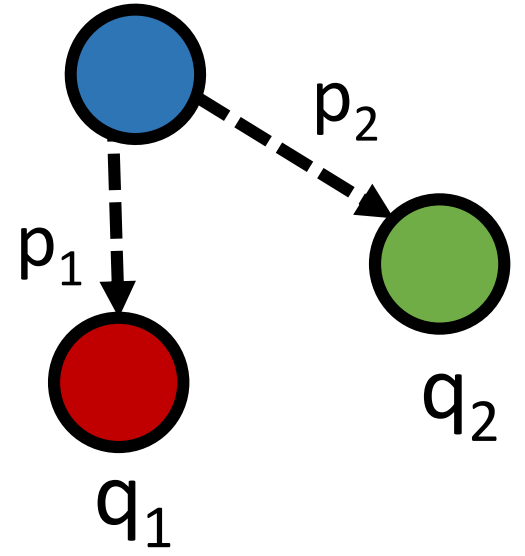


Heuristic Algorithm

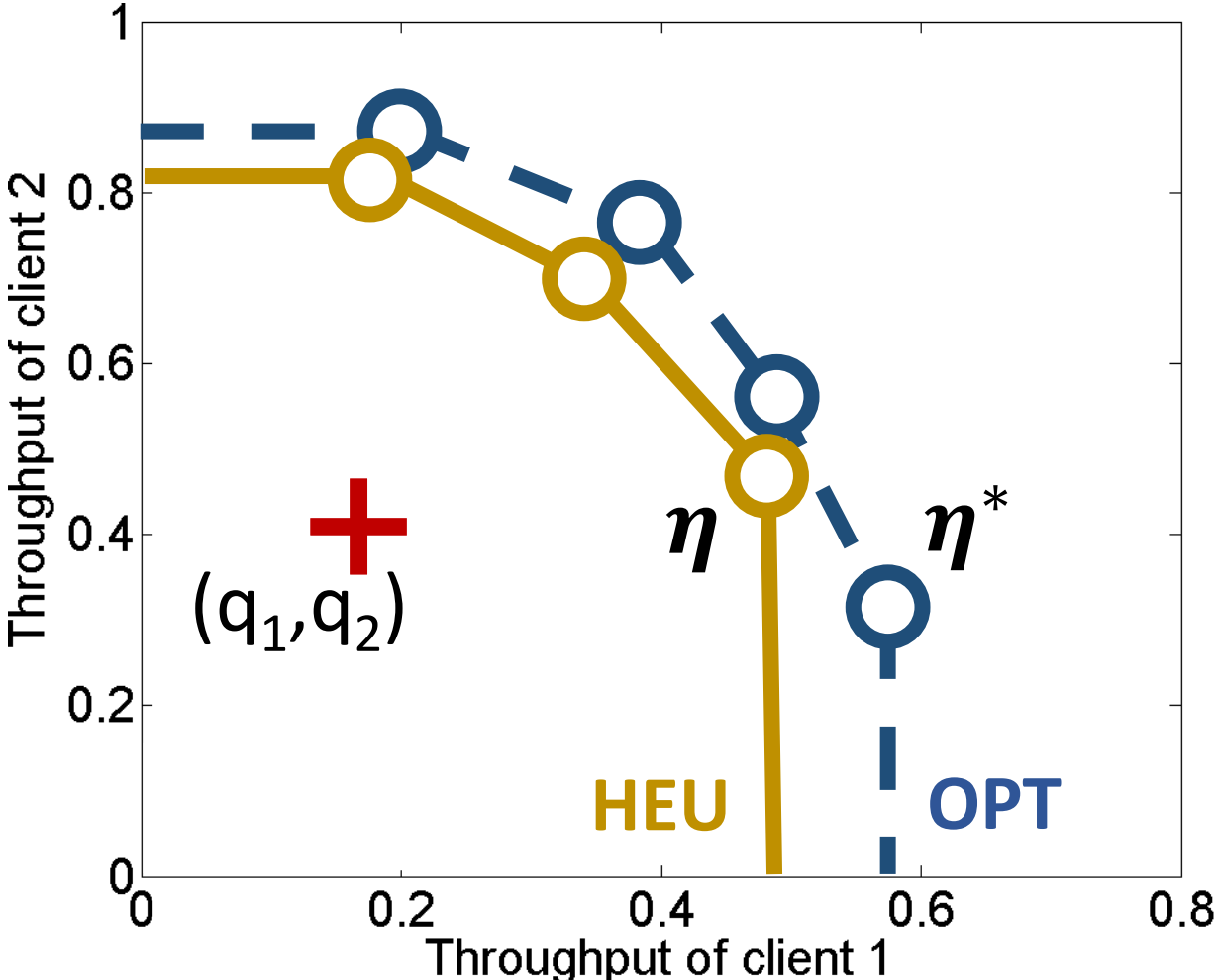
Heuristic Algorithm



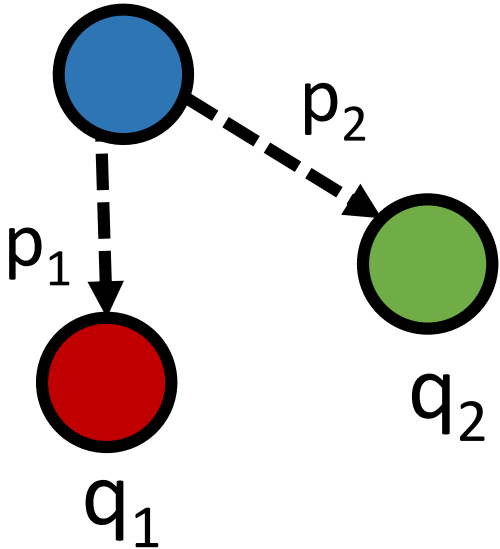
N
T
d
p₁
p₂



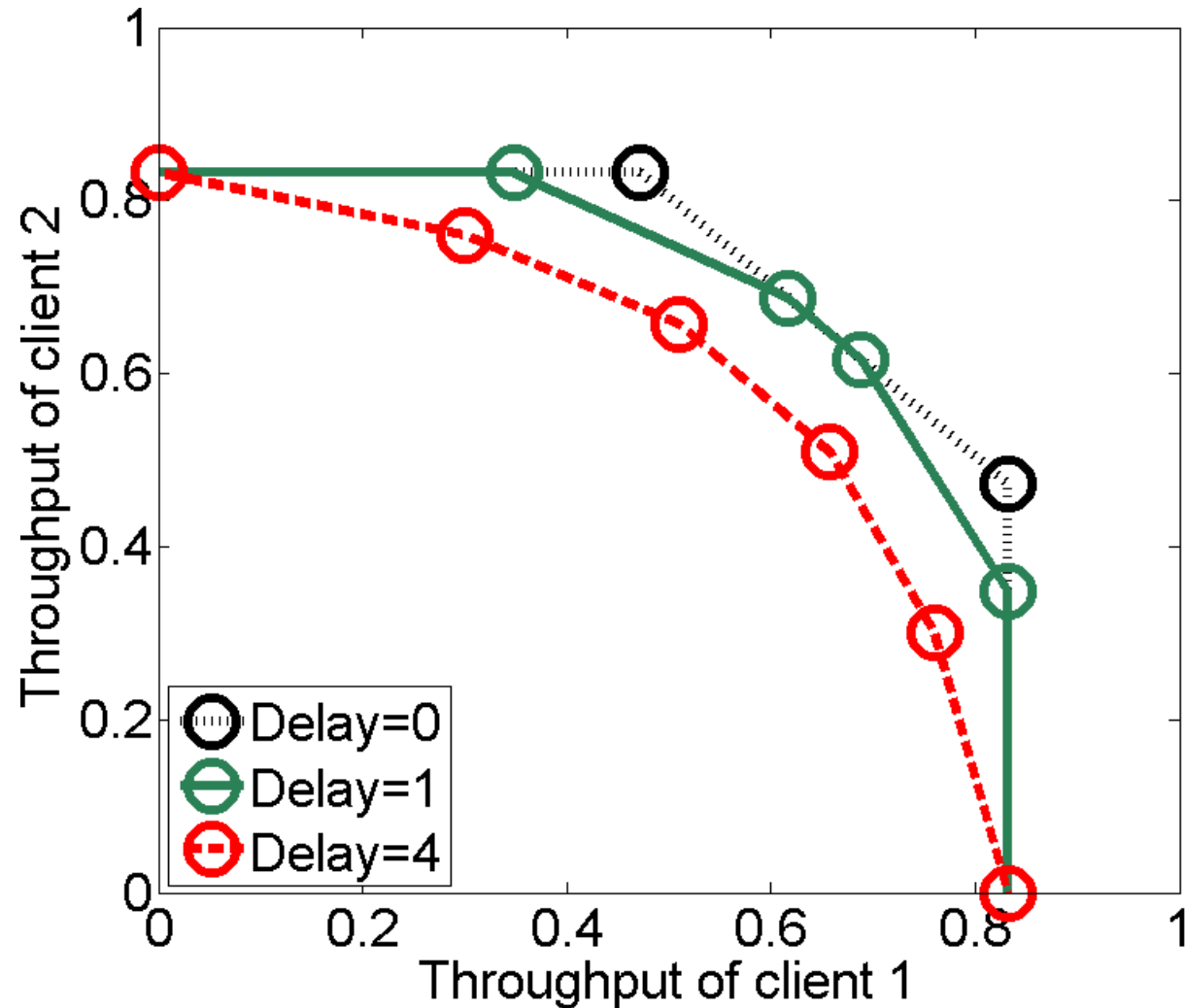
Heuristic Algorithm



N
T
d
 p_1
 p_2



Insights into the **Optimal** Policies



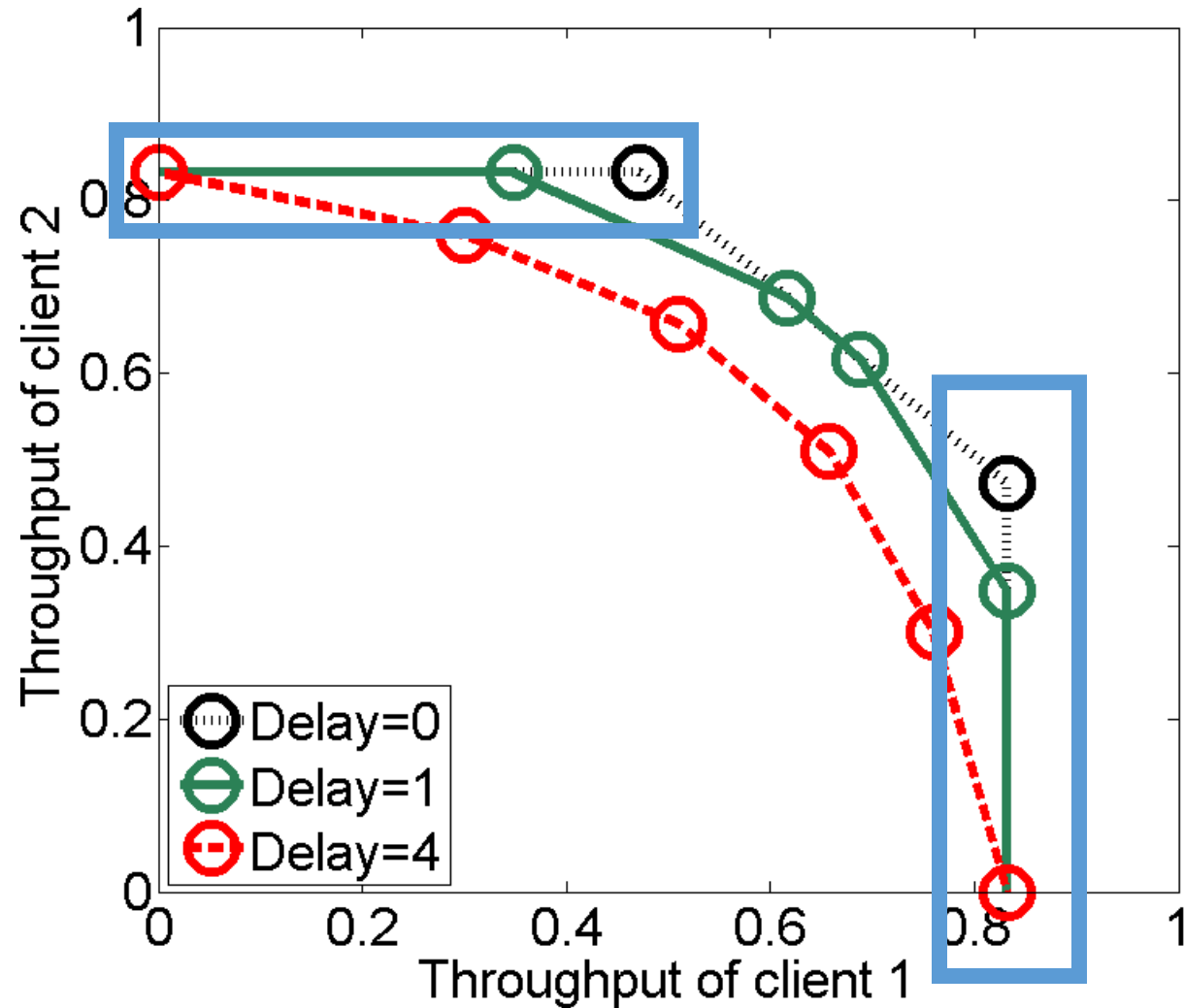
$N = 2$

$T = 5$

$d = 0, 1, 4$

$p_1 = p_2 = 0.3$

Insights into the Optimal Policies



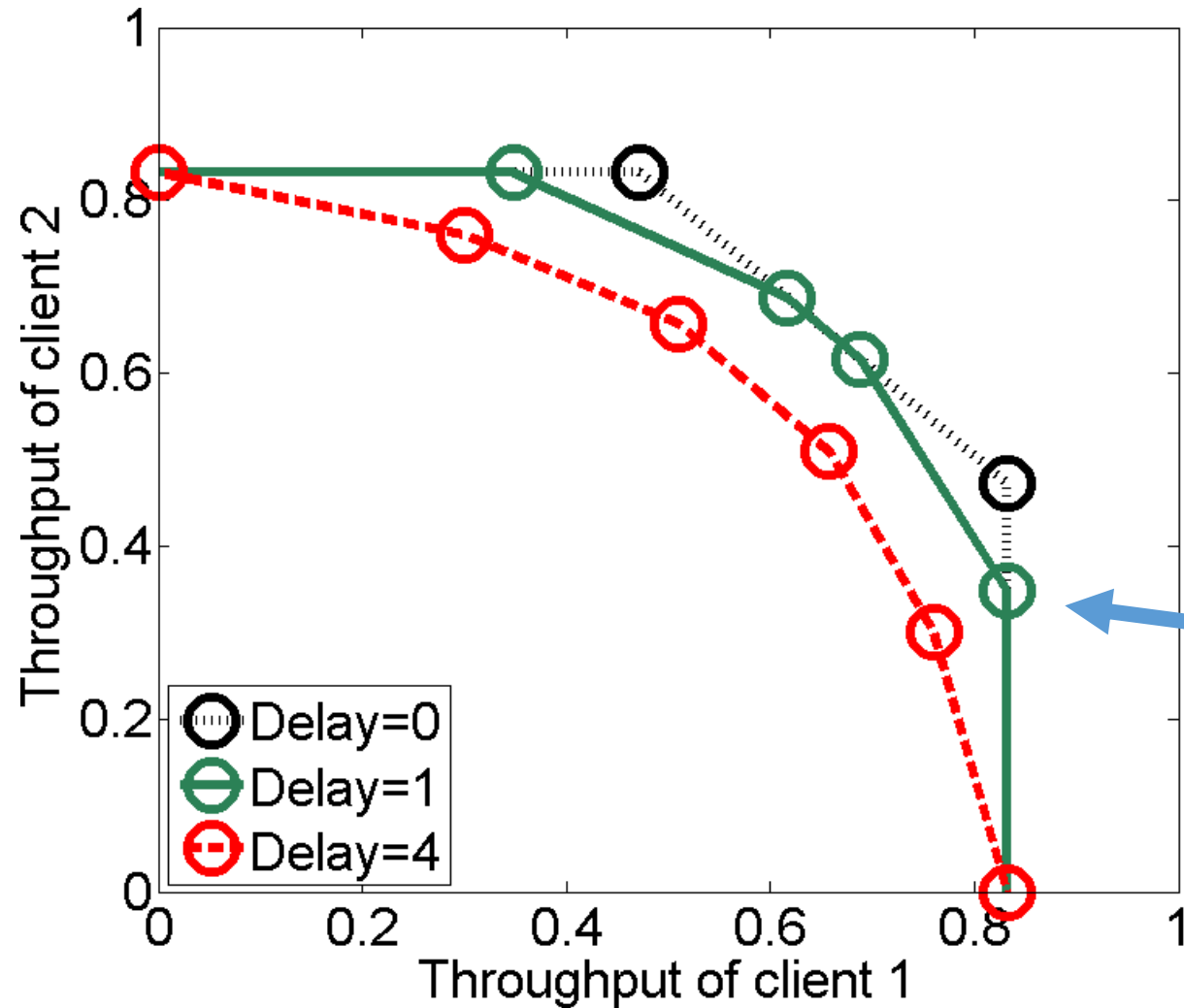
$N = 2$

$T = 5$

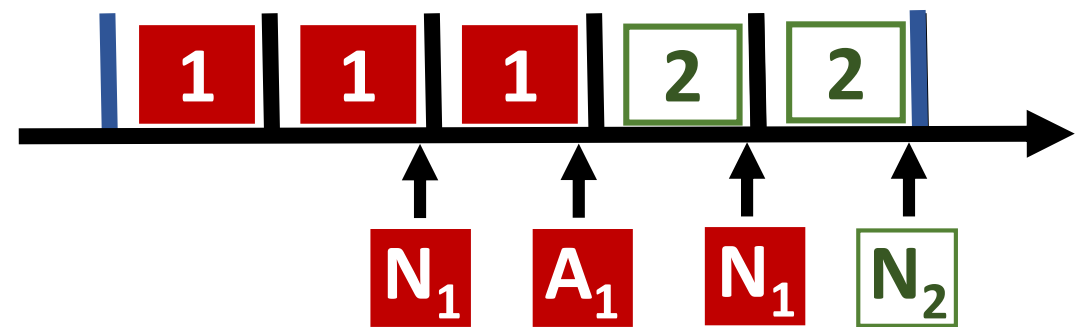
$d = 0, 1, 4$

$p_1 = p_2 = 0.3$

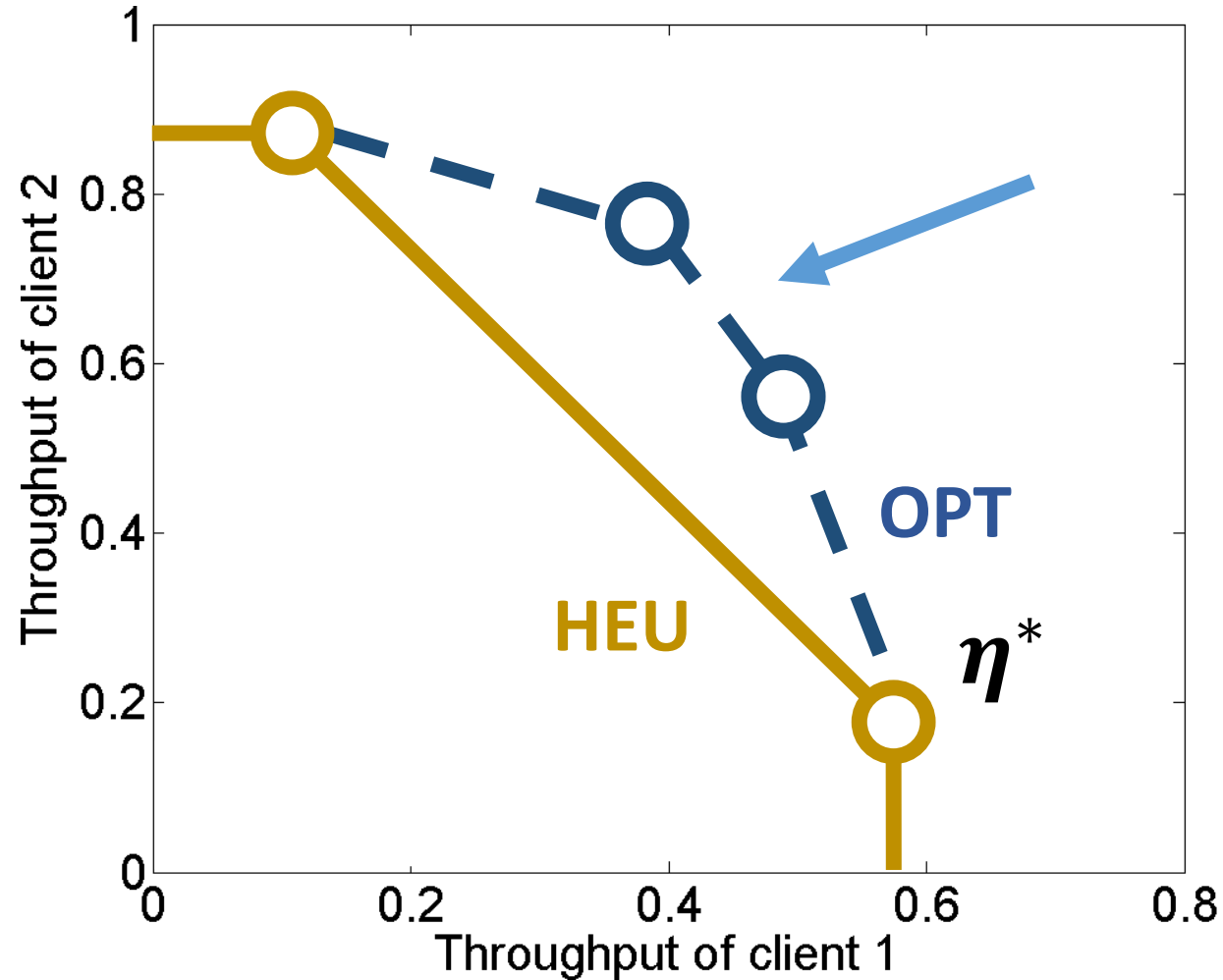
Insights into the Optimal Policies



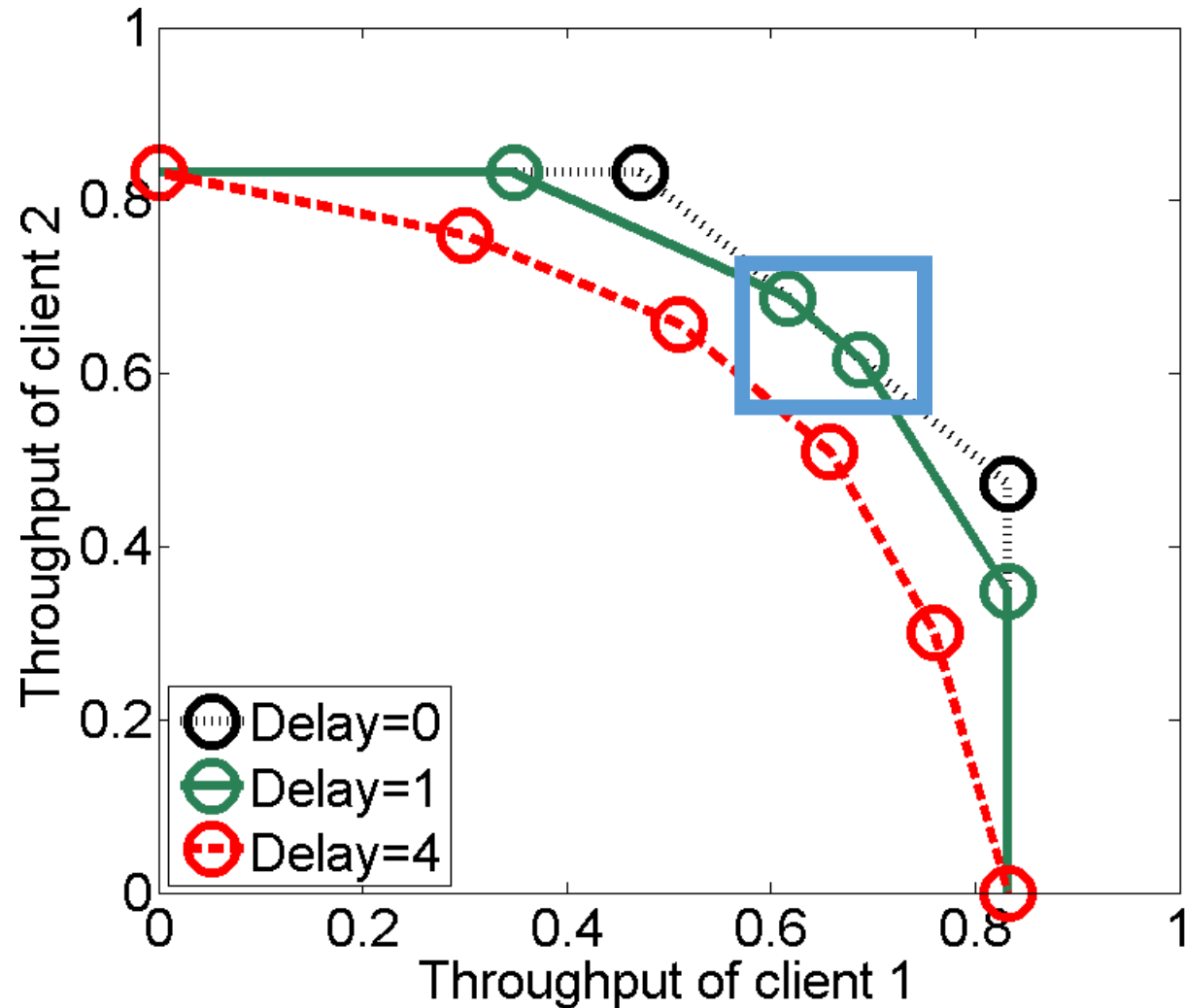
$N = 2$
 $T = 5$
 $d = 0, 1, 4$
 $p_1 = p_2 = 0.3$



Insights into the Optimal Policies



Insights into the Optimal Policies



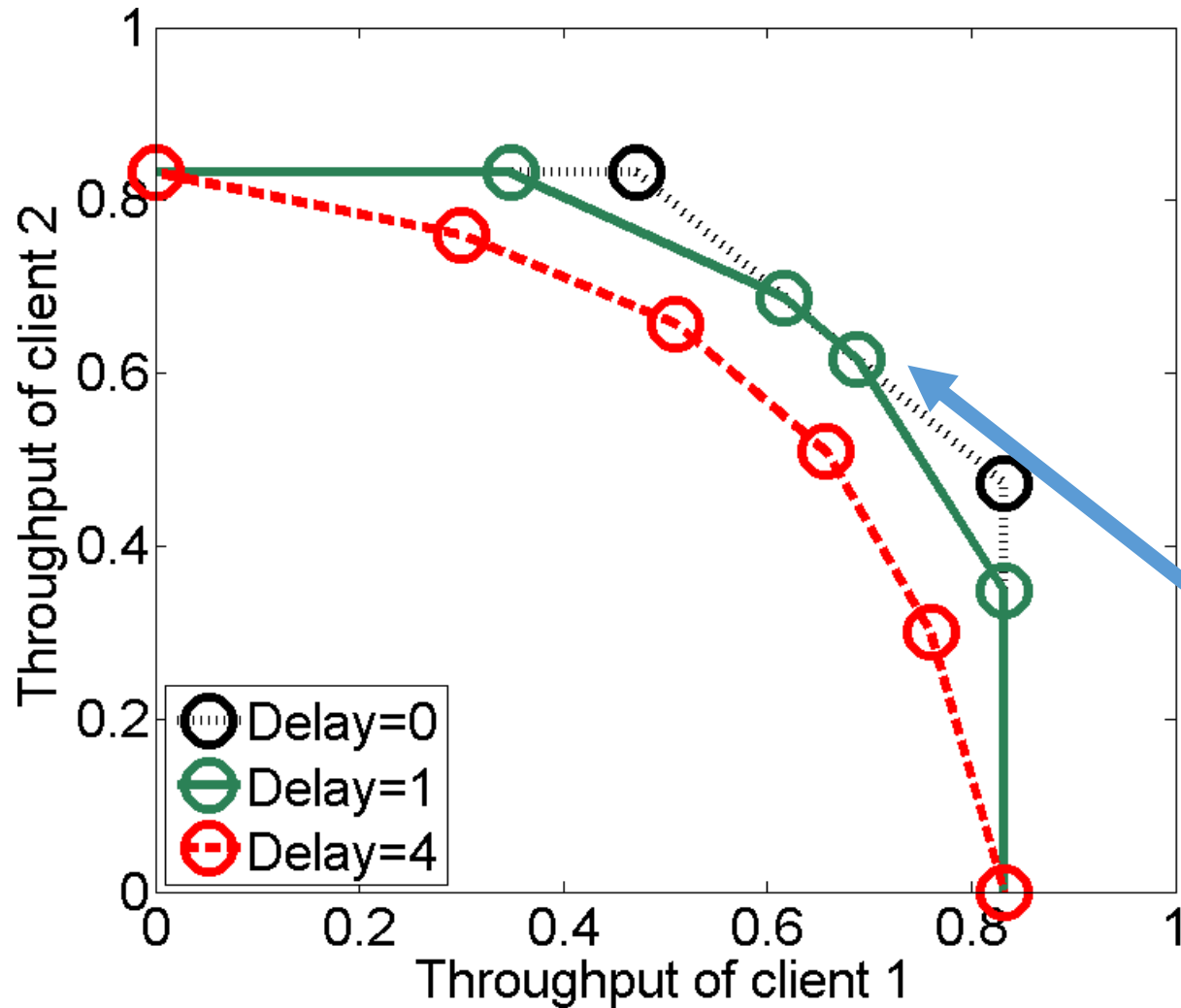
$N = 2$

$T = 5$

$d = 0, 1, 4$

$p_1 = p_2 = 0.3$

Insights into the Optimal Policies

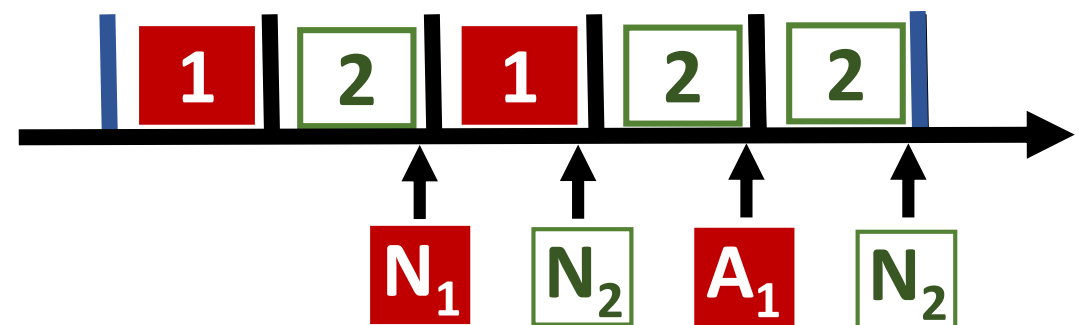


$N = 2$

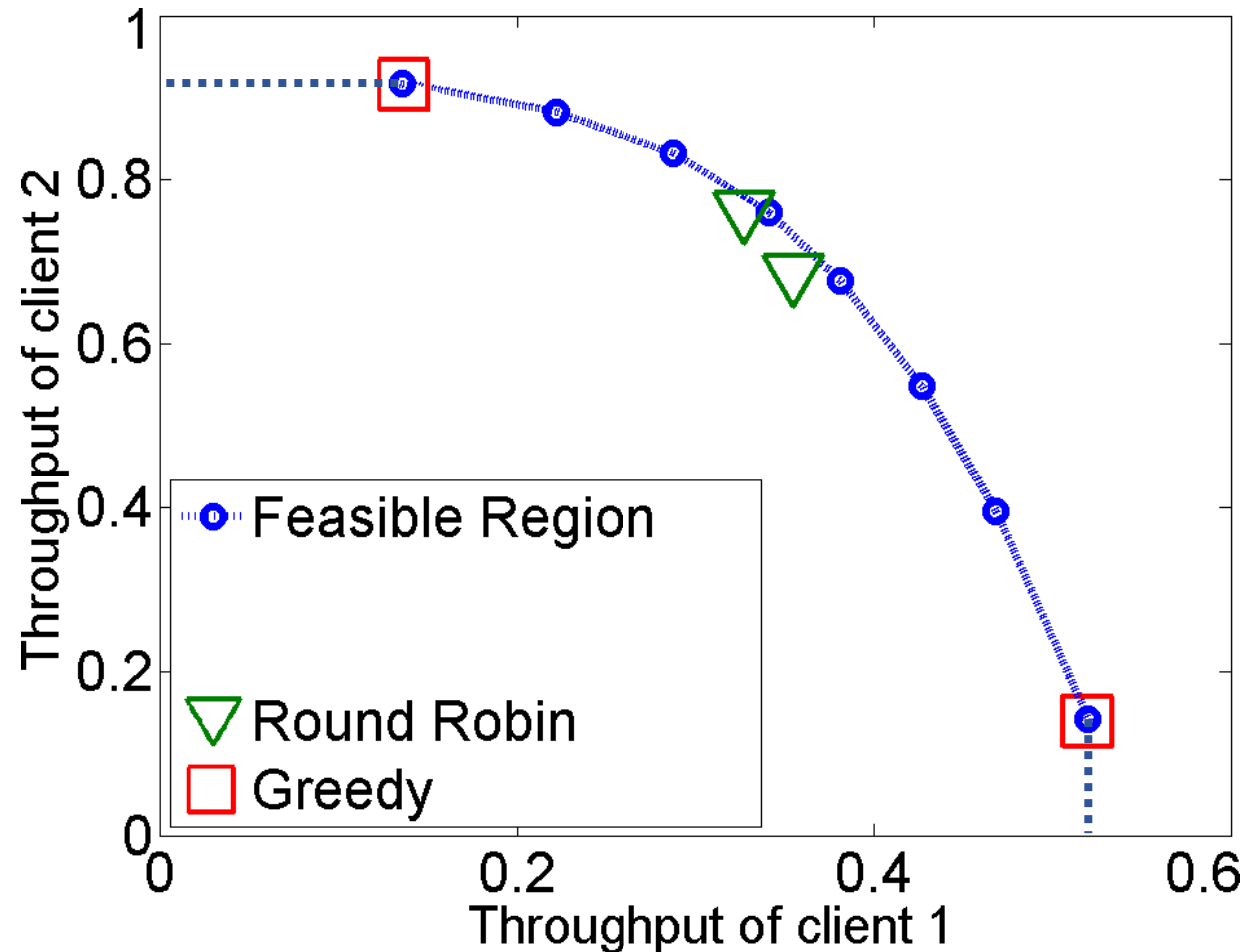
$T = 5$

$d = 0, 1, 4$

$p_1 = p_2 = 0.3$



Optimal vs Heuristic



$N = 2$

$T = 7$

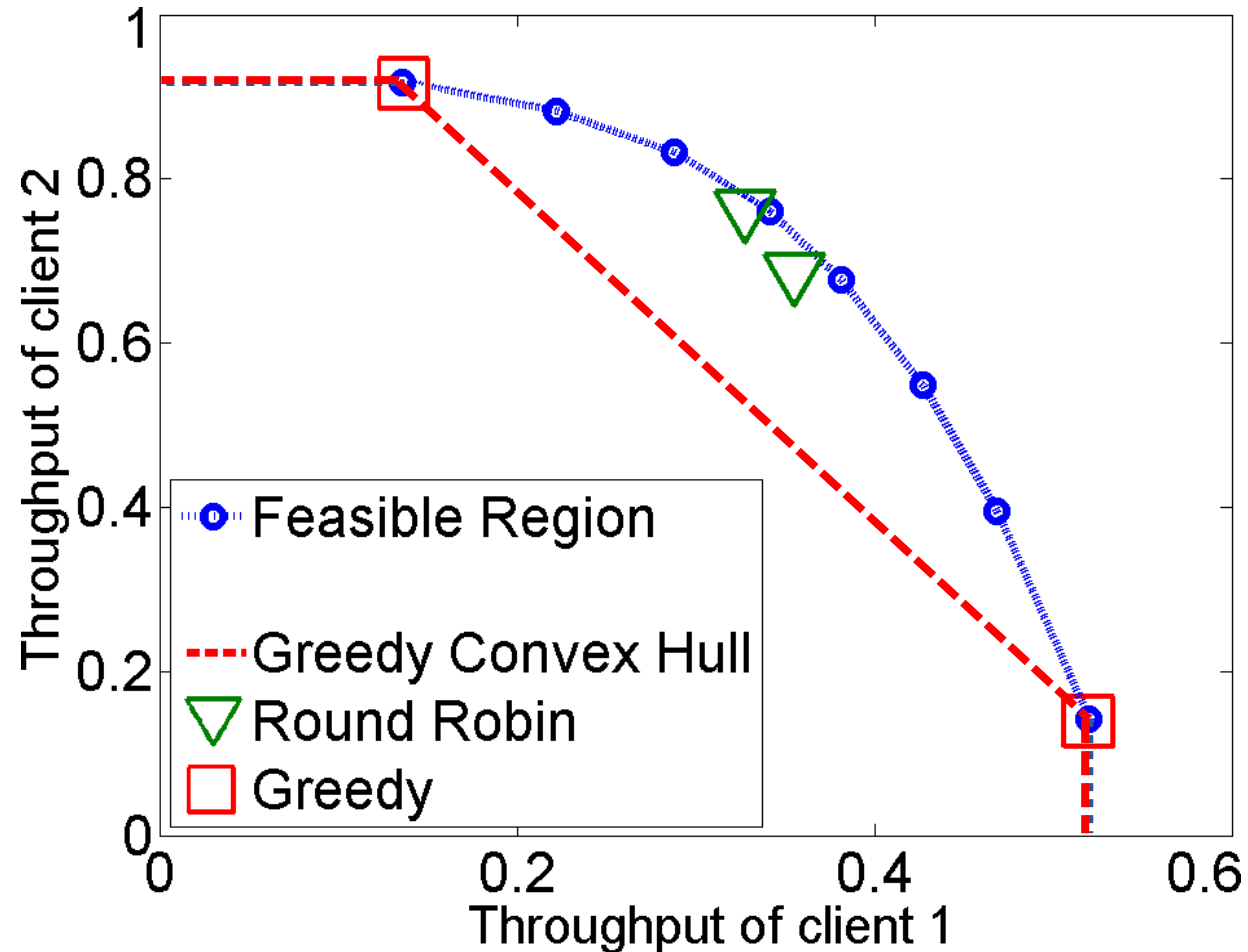
$d = 3$

$p_1 = 0.1$

$p_2 = 0.3$

frames = 5×10^4

Optimal vs Heuristic



$N = 2$

$T = 7$

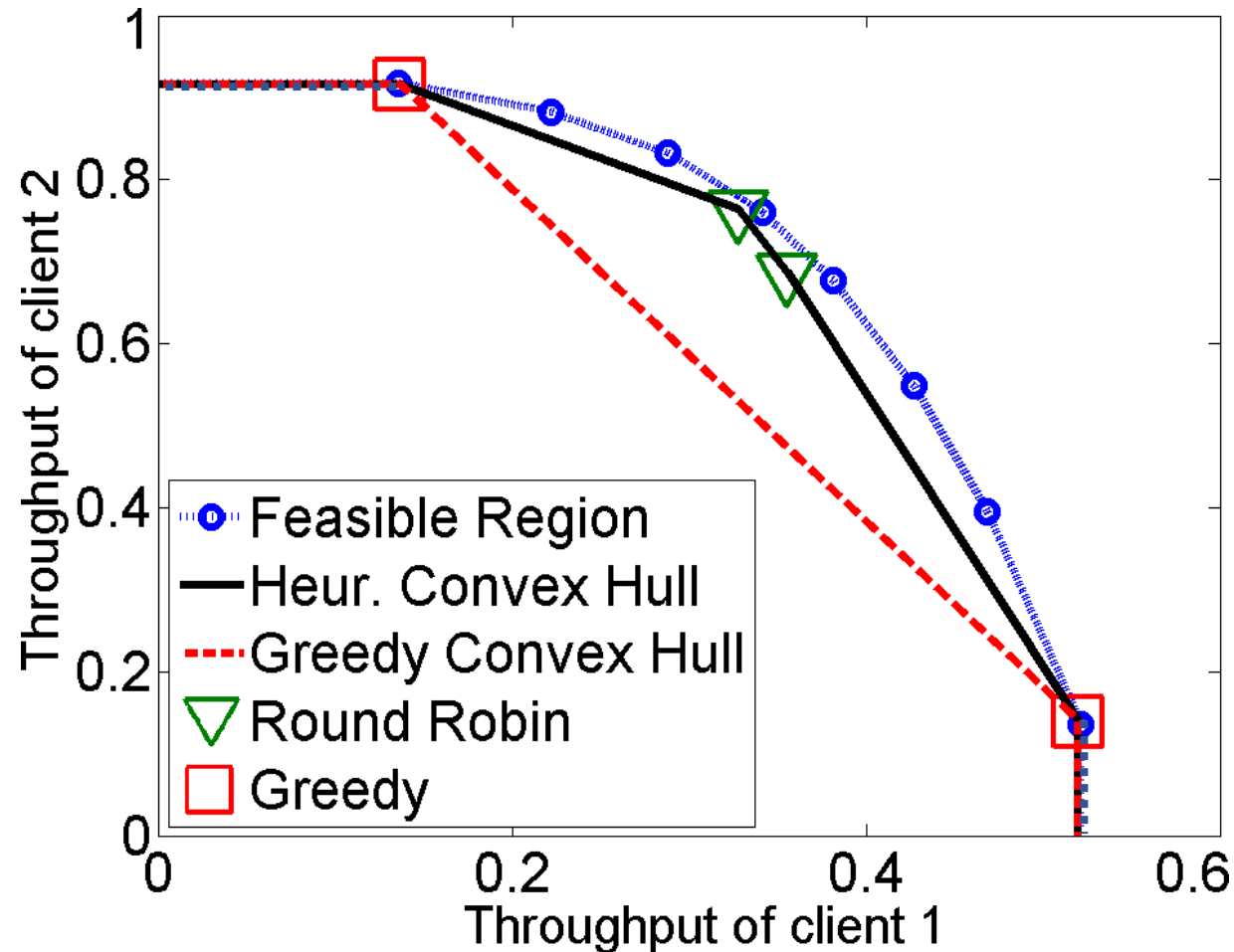
$d = 3$

$p_1 = 0.1$

$p_2 = 0.3$

frames = 5×10^4

Optimal vs Heuristic



$N = 2$

$T = 7$

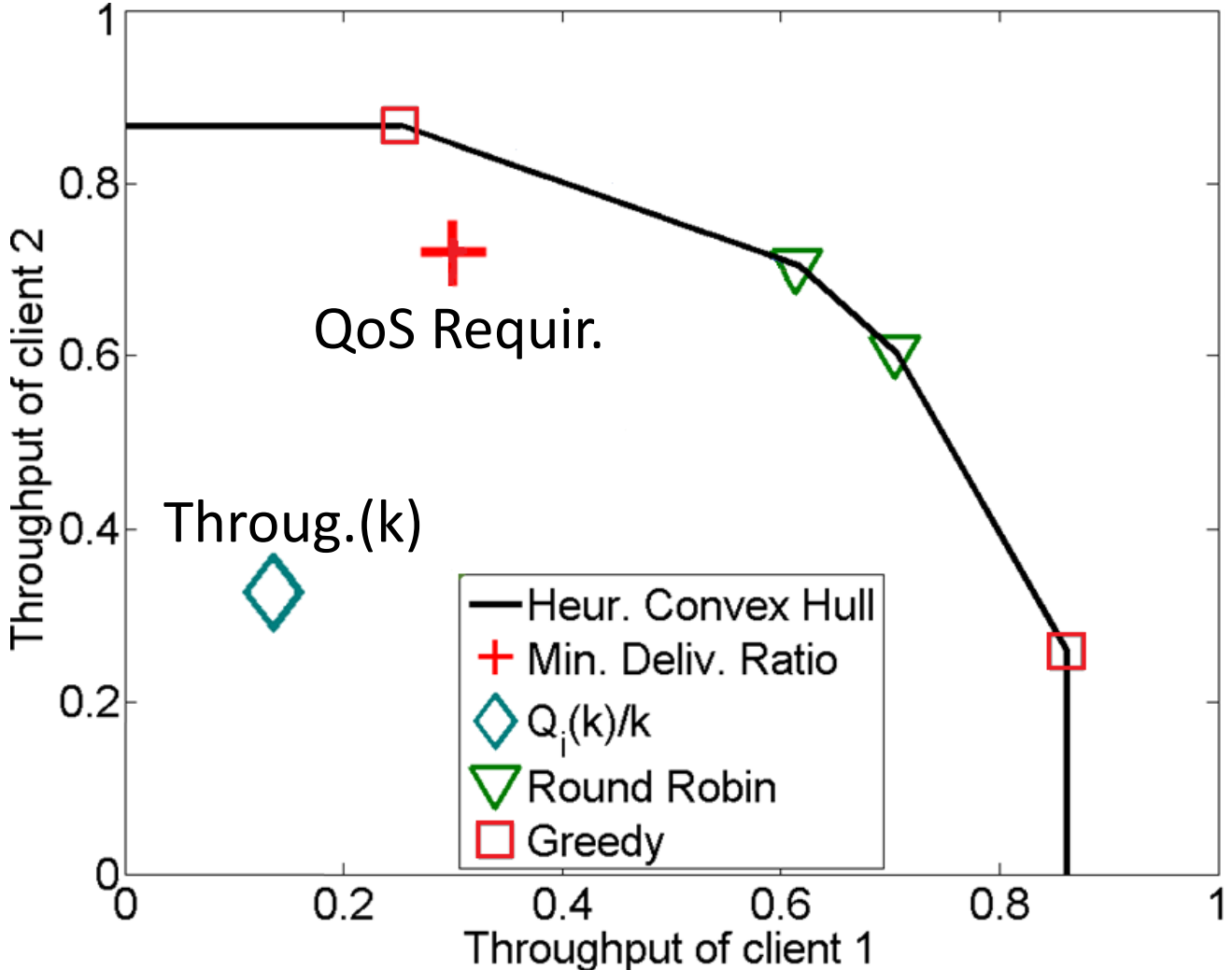
$d = 3$

$p_1 = 0.1$

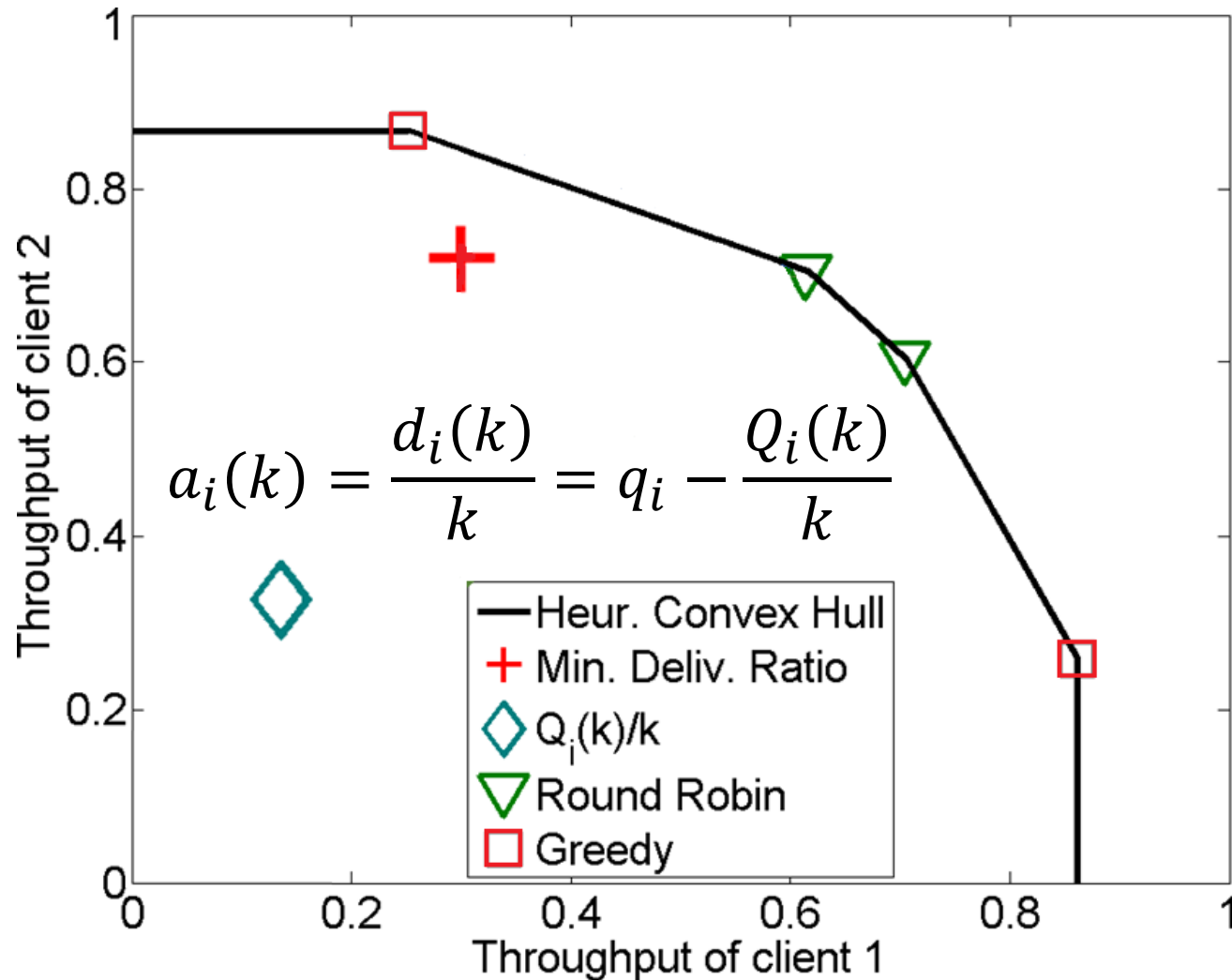
$p_2 = 0.3$

frames = 5×10^4

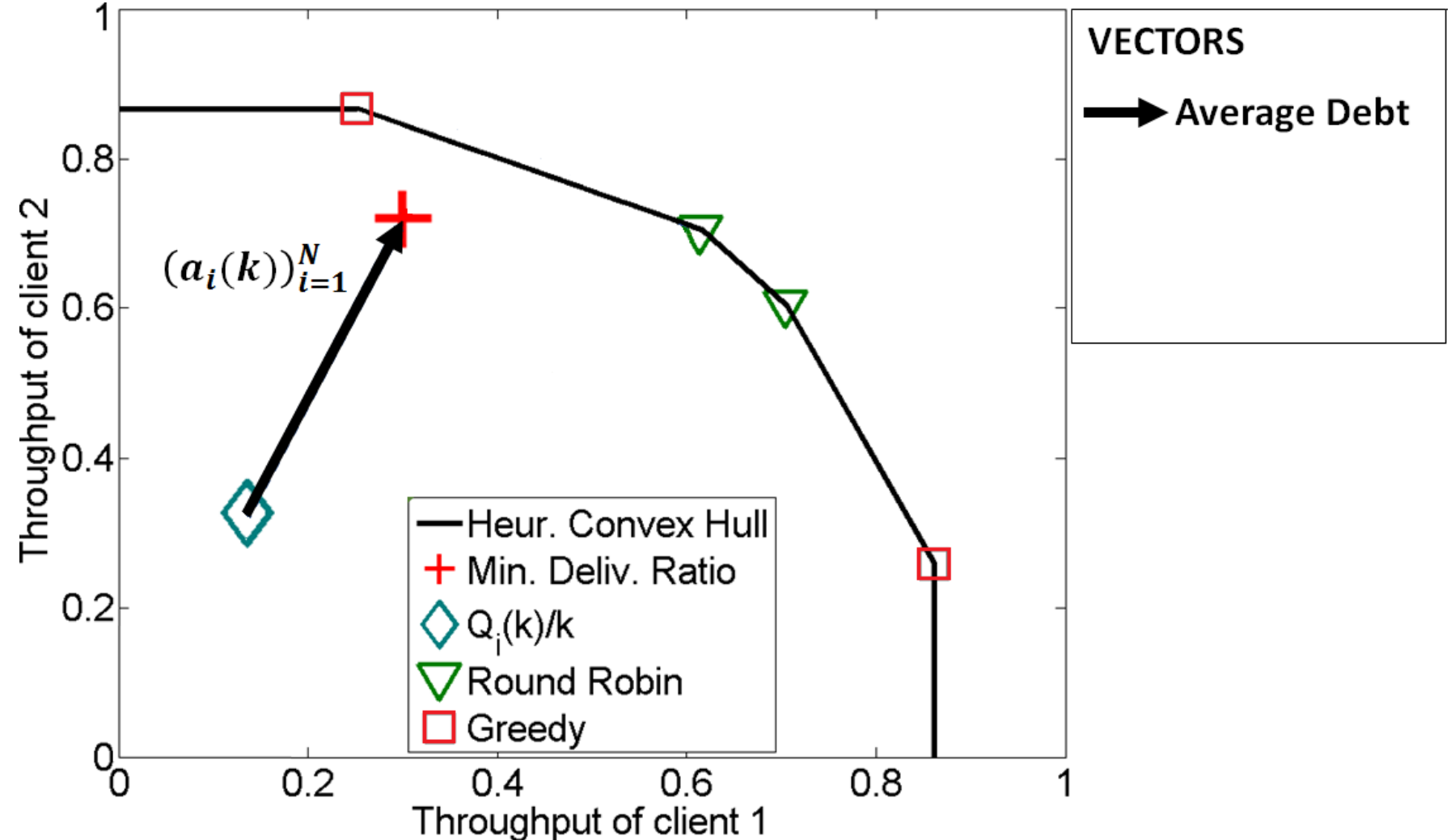
Heuristic Algorithm



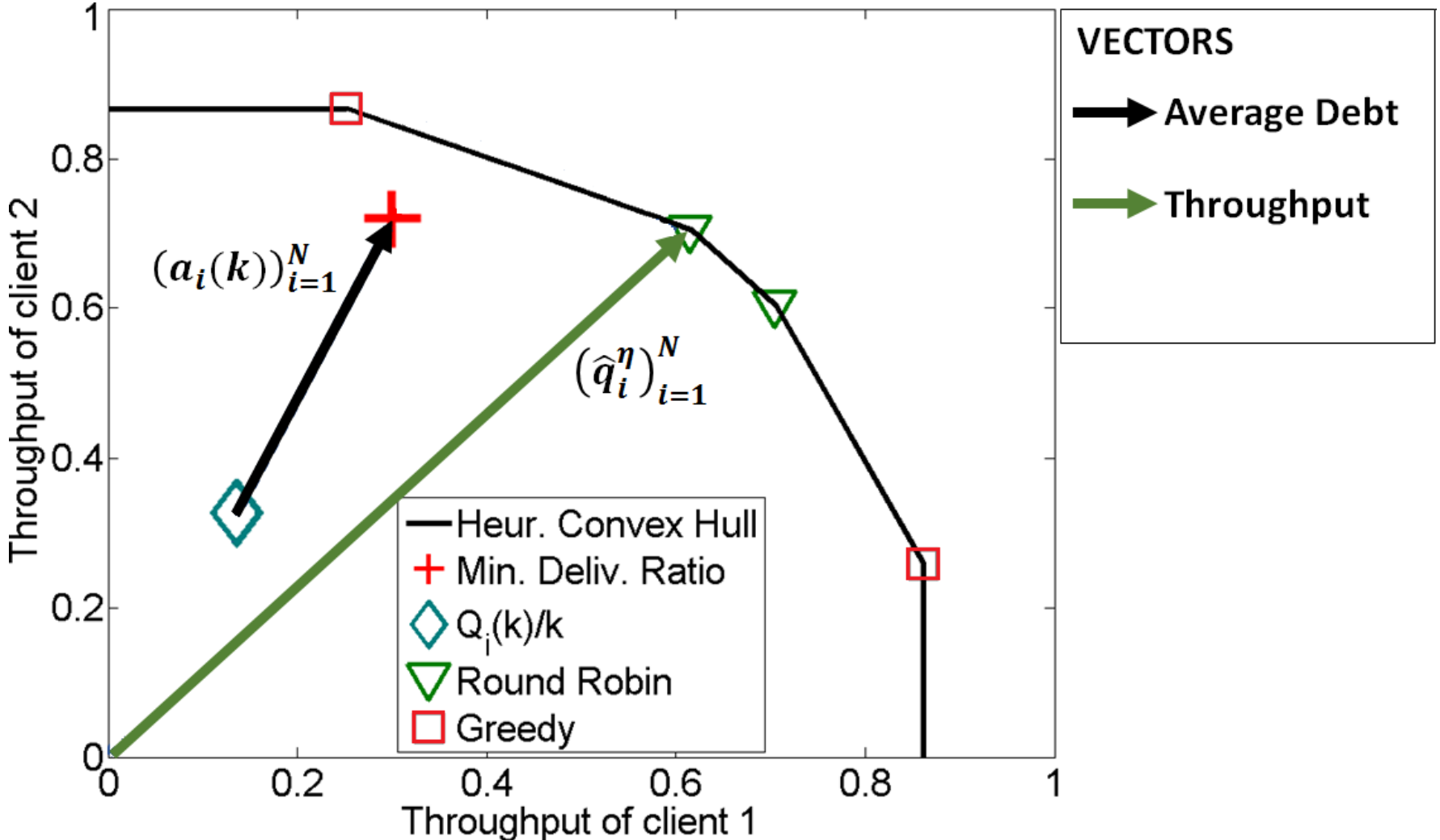
Heuristic Algorithm



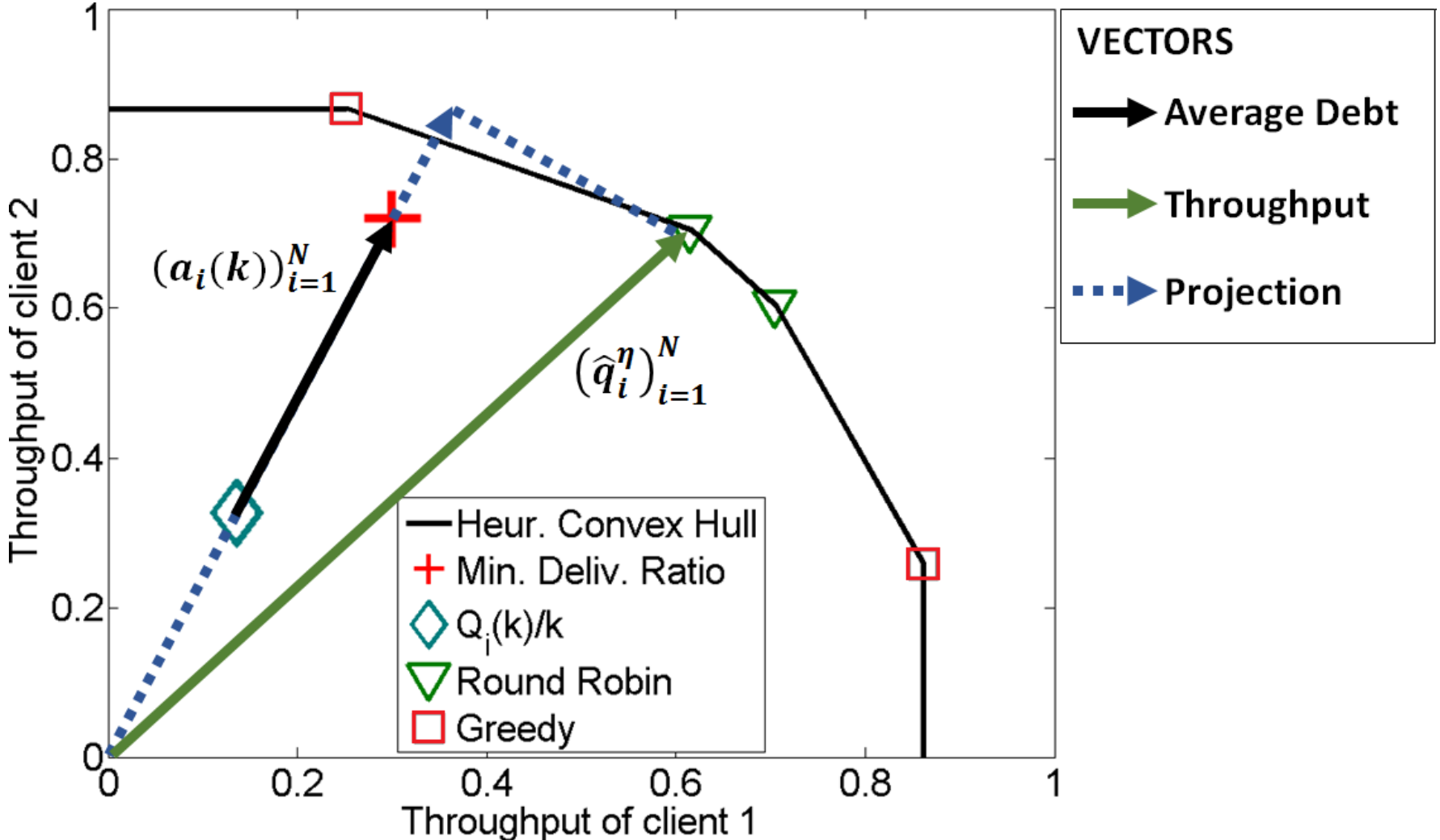
Heuristic Algorithm



Heuristic Algorithm



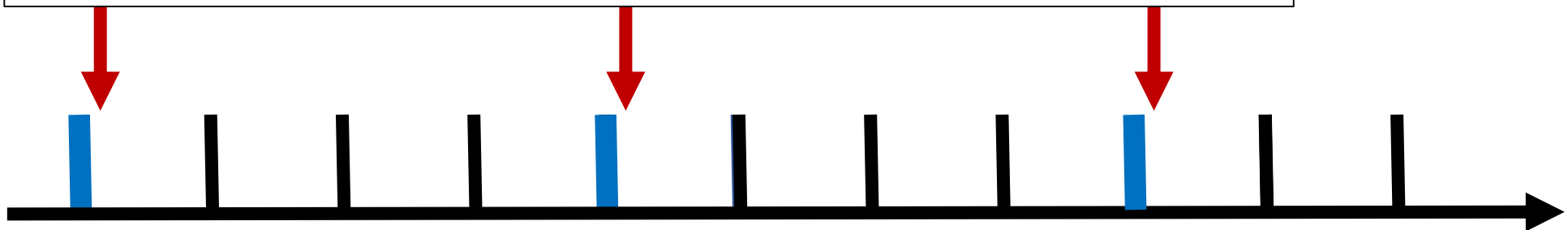
Heuristic Algorithm



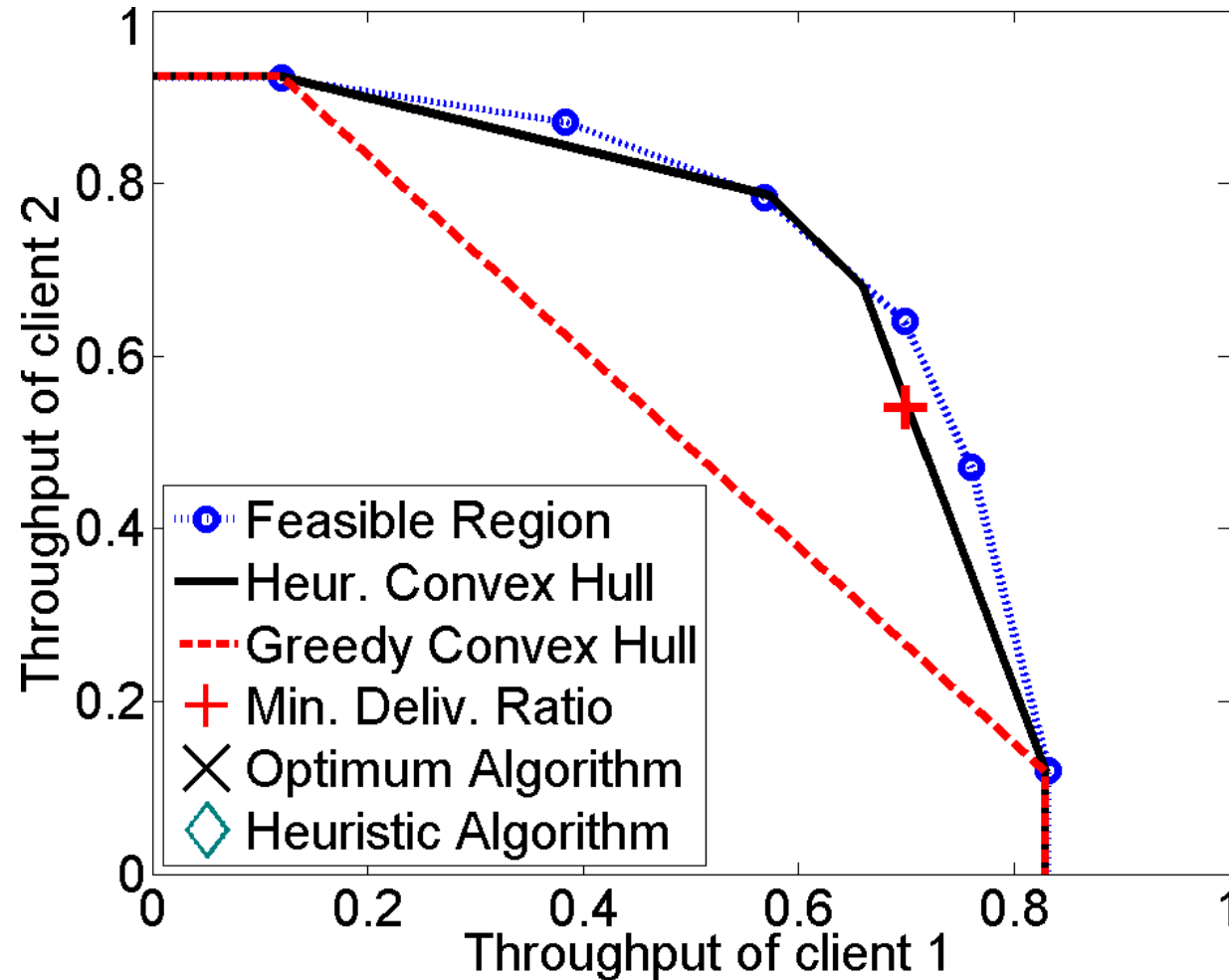
Heuristic Algorithm

Heuristic Algorithm

- $a_i(k) = q_i - Q_i(k)/k$
- $\max_{\eta \in \text{set}} \{\text{projection}\}$
- Employ η



Simulations – Opt. and Heur.



$N = 2$

$T = 5$

$d = 3$

$p_1 = 0.3$

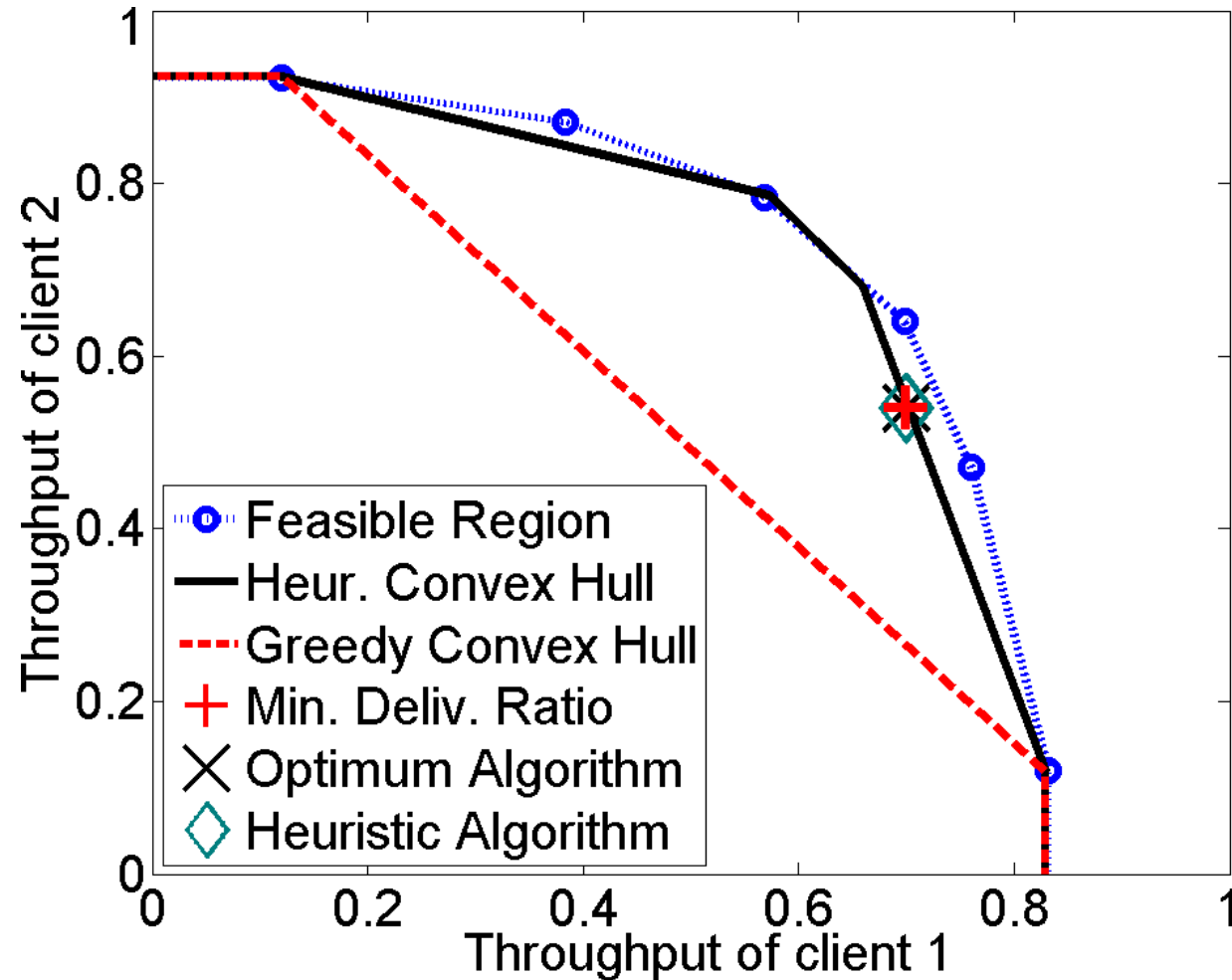
$p_2 = 0.4$

$q_1 = 0.7$

$q_2 = 0.54$

frames = 5×10^4

Simulations – Opt. and Heur.



$N = 2$

$T = 5$

$d = 3$

$p_1 = 0.3$

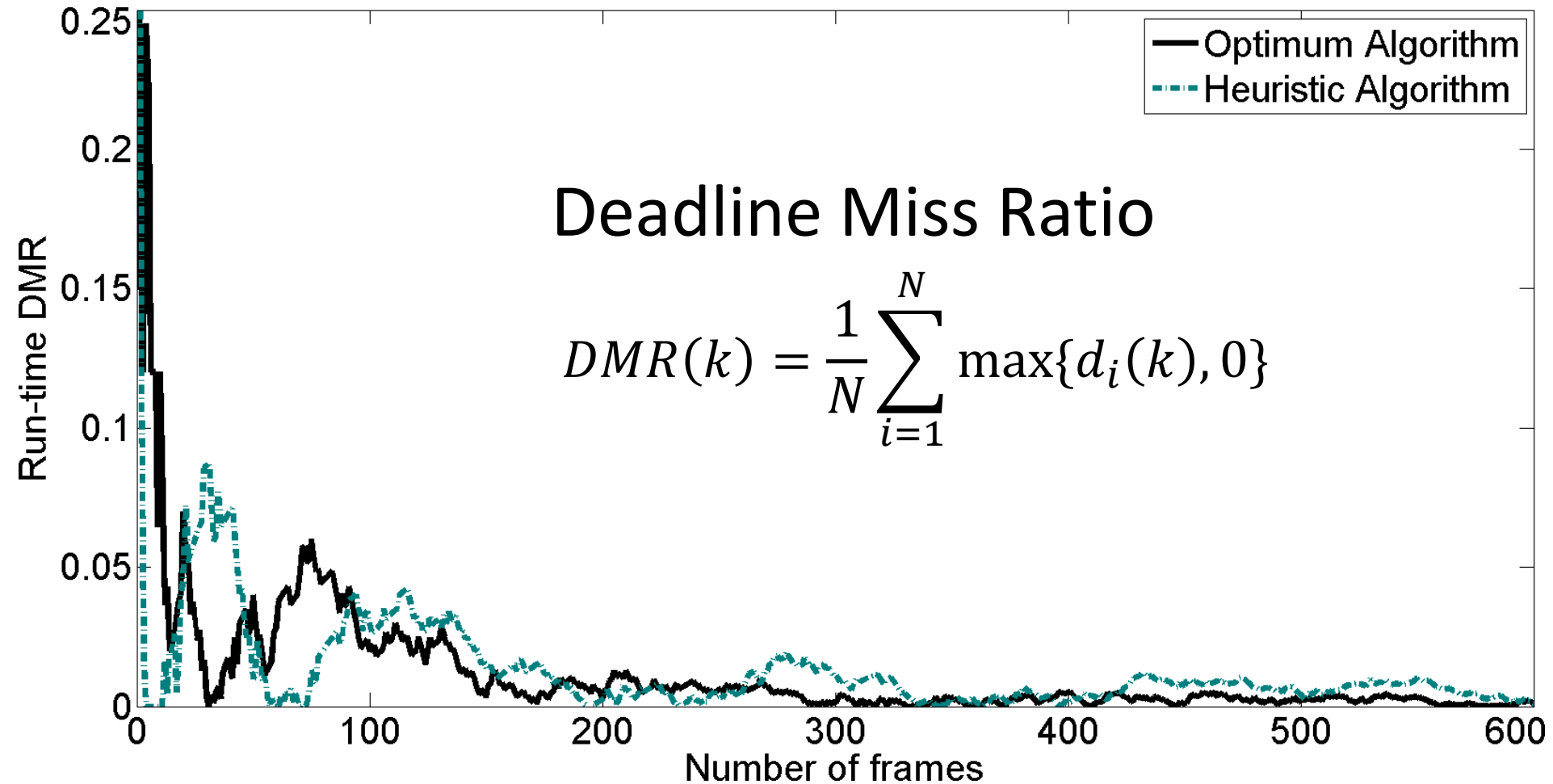
$p_2 = 0.4$

$q_1 = 0.7$

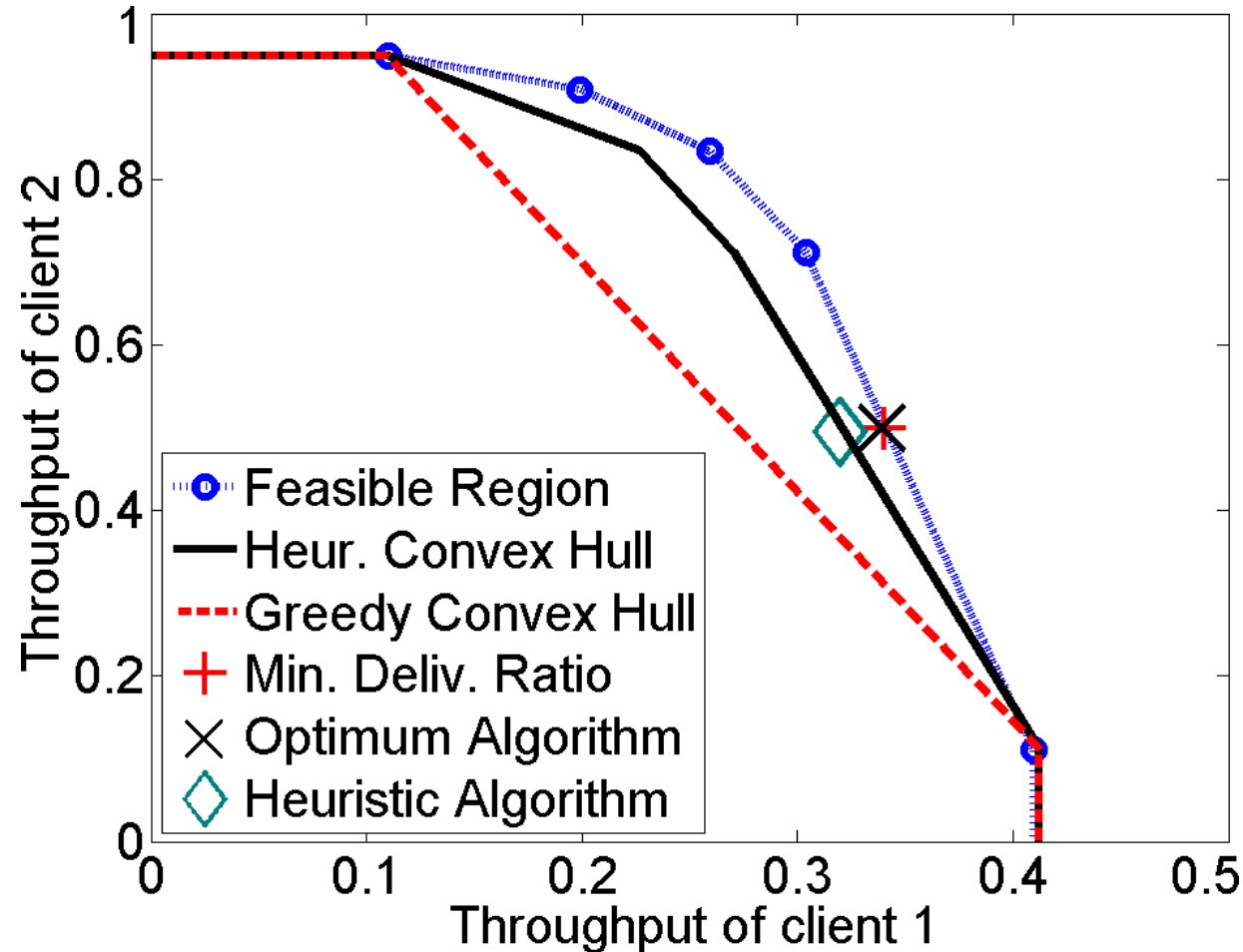
$q_2 = 0.54$

frames = 5×10^4

Simulations – Opt. and Heur.



Simulations – Opt. and Heur.



$N = 2$

$T = 5$

$d = 2$

$p_1 = 0.1$

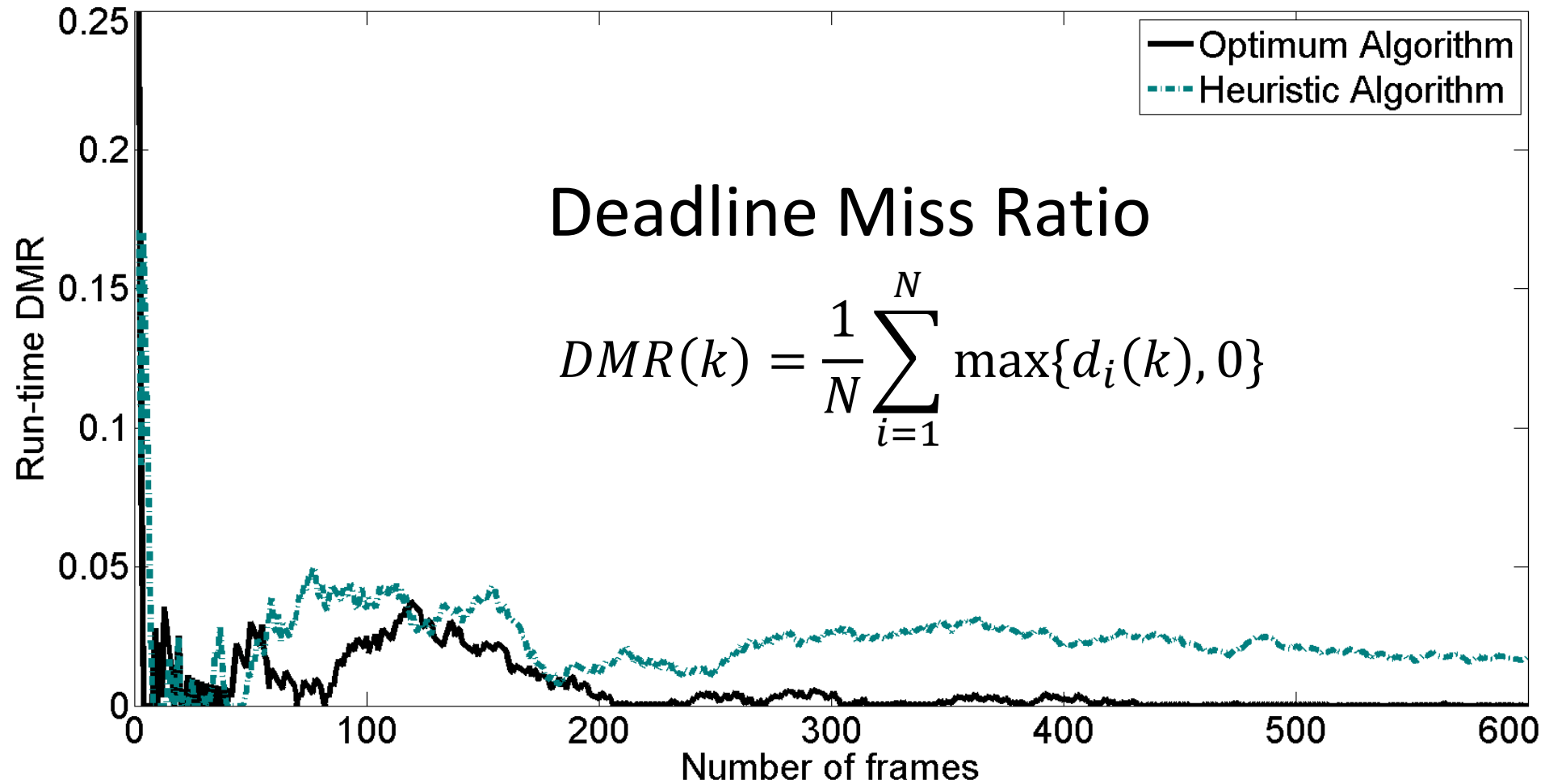
$p_2 = 0.45$

$q_1 = 0.34$

$q_2 = 0.5$

frames = 5×10^4

Simulations – Opt. and Heur.



Contributions / Topics

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- Solution
- Feasible Region
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- Low-complexity Heuristic Algorithm